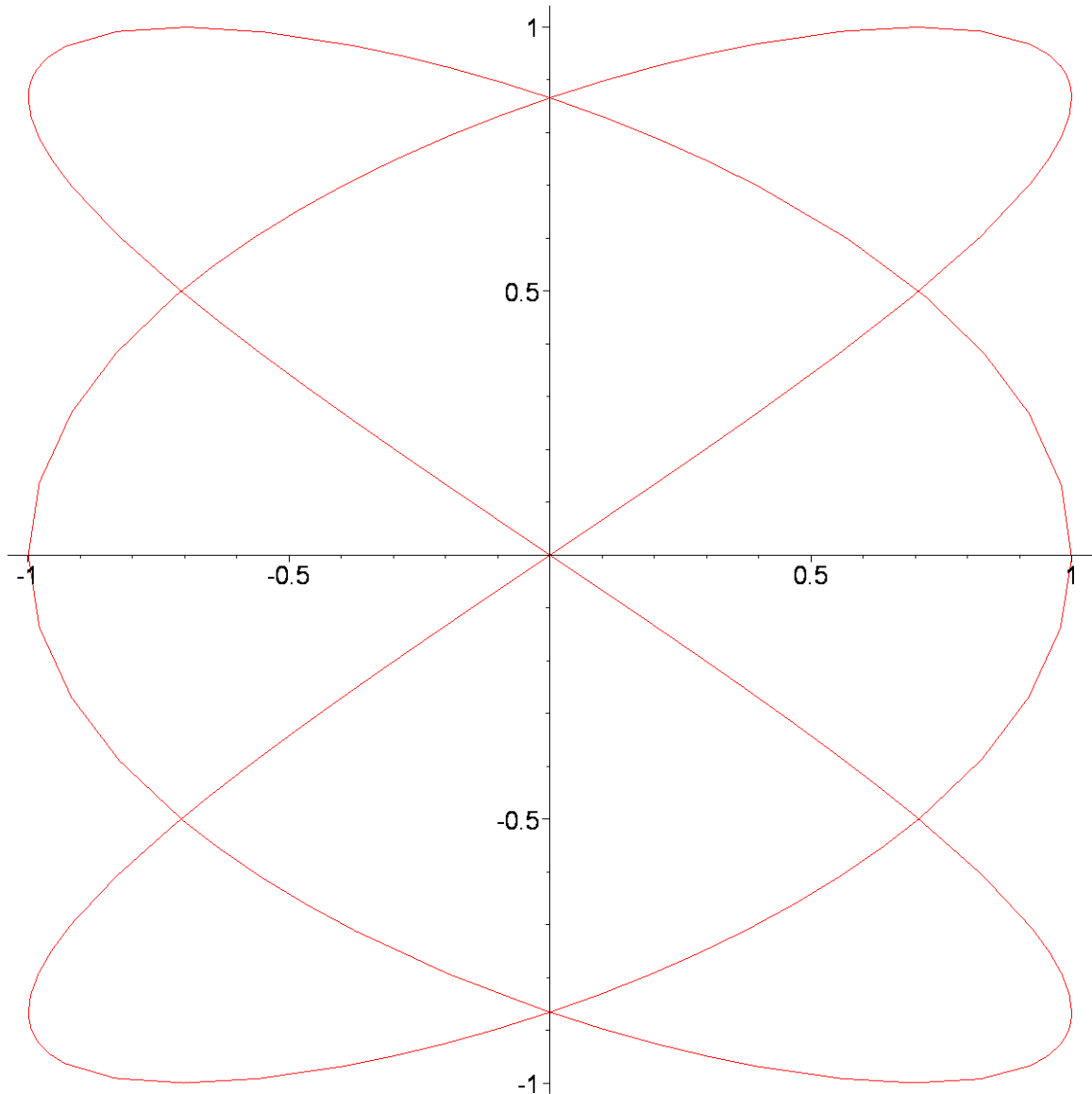
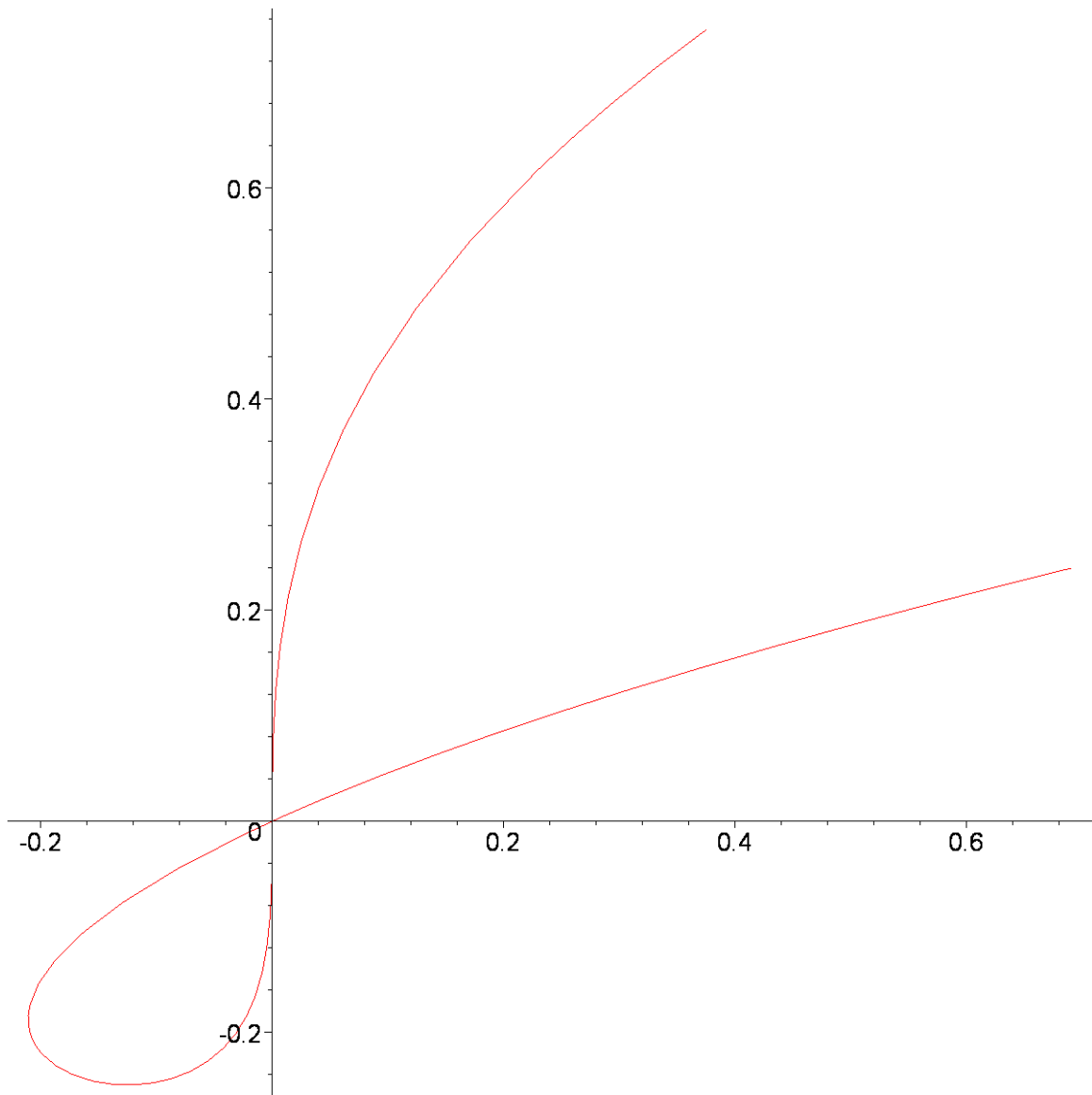


```
> ##### FEUILLE N3 237
##### Exercice 1.
plot([cos(3*t), sin(2*t), t=-Pi..Pi]);
```



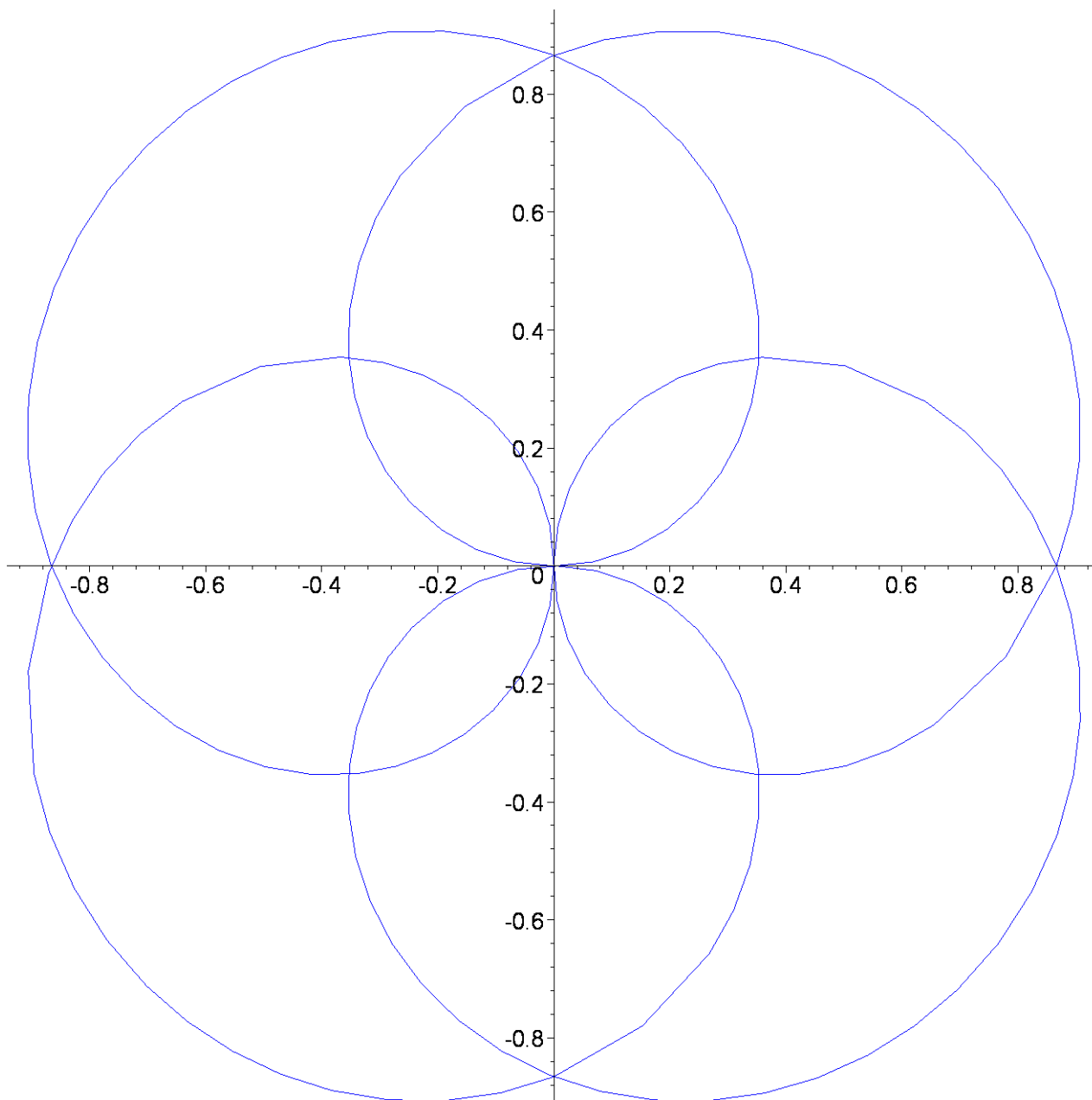
```
> ##### Exercice 2.
restart:plot([2*t^4-2*t^3,t^2-t, t=-0.5..1.2]);
```



>

```
> ##### Exercise 3.  
with(plots):  
polarplot([sin(2*t/3),t,t=0..6*Pi],color=blue);
```

Warning, the name changecoords has been redefined



> ##### Exercice 4

> with(VectorCalculus): assume(a>0):

> SetCoordinates( 'polar' );

A:=ArcLength( <a\*cos(2\*t), t>, t=0..Pi/2) ;

*polar*

$$A := 2 a \sim \text{EllipticE}\left(\frac{\sqrt{3}}{2}\right)$$

> r:=a\*cos(2\*t):simplify(int(sqrt(r^2+diff(r,t)^2),t)):

> with(VectorCalculus):assume(a>0):

> SetCoordinates( 'cartesian' );

B:=ArcLength( <2\*a\*cos(t),a\*sin(t)>, t=0..Pi/2);

*cartesian*

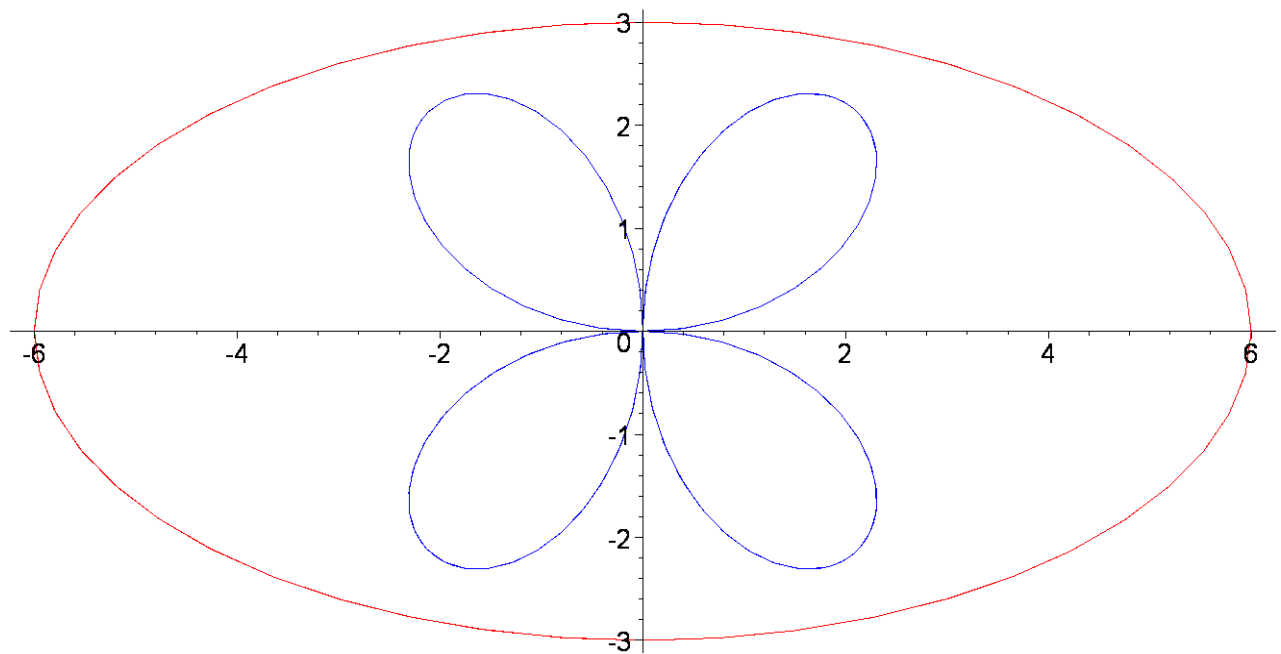
$$B := 2 a \sim \text{EllipticE}\left(\frac{\sqrt{3}}{2}\right)$$

```
> simplify(A-B);
```

$$2 a \sqrt{3} \operatorname{EllipticE}\left(\frac{\sqrt{3}}{2}\right) - 2 a \sqrt{3} \operatorname{EllipticE}\left(\frac{\sqrt{3}}{2}\right)$$

```
> with(plots):P1:=polarplot([3*sin(2*t),t,t=0..4*Pi],color=blue):  
P2:=plot([6*cos(t),3*sin(t),t=0..4*Pi],color=red):  
display(P1,P2, scaling=CONSTRAINED);
```

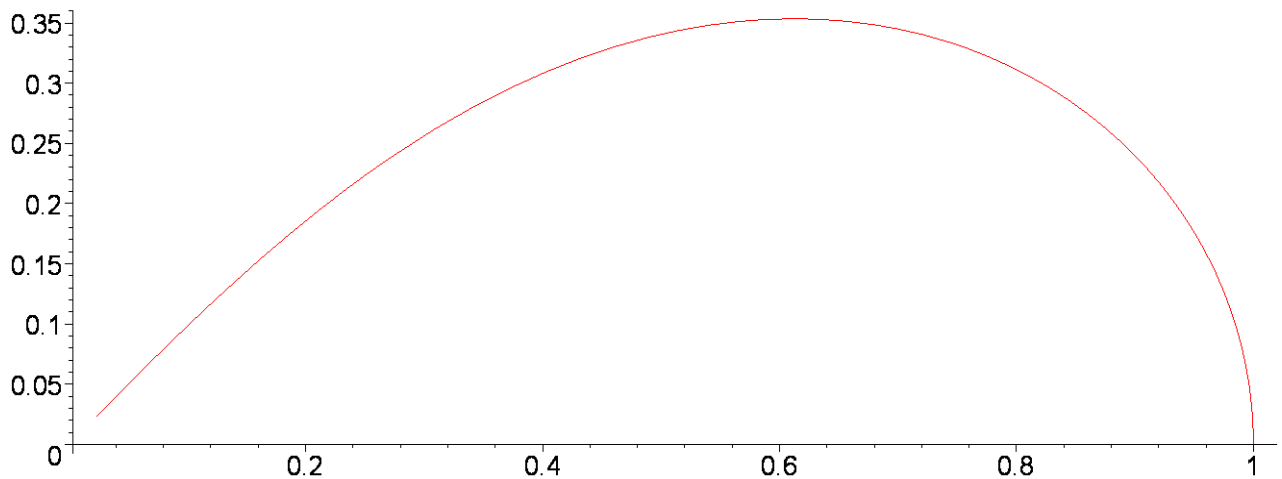
Warning, the name changecoords has been redefined



```
> ##### Exercise 5.  
restart:with(plots):  
P:=polarplot([(cos(2*t))^(1/2), t, t=0..Pi/4]):
```

```
> display(P, scaling=CONSTRAINED);
```

Warning, the name changecoords has been redefined



```
> r:=(cos(2*t))^(1/2);rp:=diff(r,t);
ds:=simplify((sqrt(r^2+rp^2))*dt;
```

$$r := \sqrt{\cos(2t)}$$

$$rp := -\frac{\sin(2t)}{\sqrt{\cos(2t)}}$$

$$ds := \sqrt{\frac{1}{\cos(2t)}} dt$$

```
>
```

```
> #####
##### Exercice 6.
SetCoordinates('polar');
ArcLength(<1, t>, t=0..2*Pi);
```

*polar*  
 $2\pi$

```

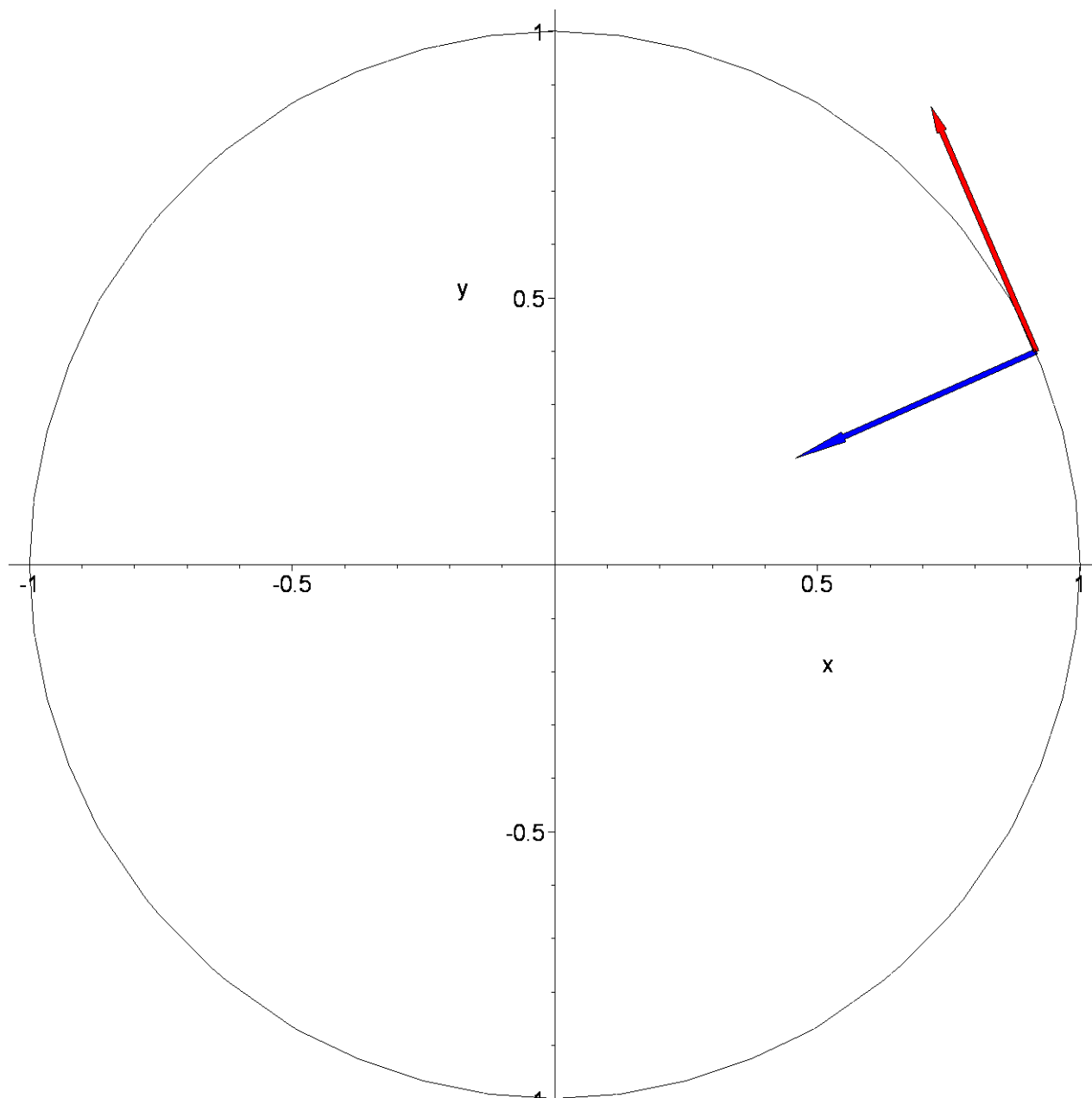
> restart;F:=x^2+y^2-1;Fx:=diff(F, x);Fy:=diff(F, y);
y0:=0.3; x0:=sqrt(-y0^2+1);

          F := x2 + y2 - 1
          Fx := 2 x
          Fy := 2 y
          y0 := 0.3
          x0 := 0.9539392014
> with(plots):b0:=implicitplot(F=0, x=-2..2,y=-2..2,color=black ,
numpoints=1000):
y0:=0.4; x0:=sqrt(-y0^2+1);
Fx0:=eval( Fx, [x=x0, y=y0]);
Fy0:=eval( Fy, [x=x0, y=y0]);
l0:=(Fx0^2+Fy0^2)^(1/2);
b1 := arrow(<x0,y0>, <-Fy0/l0,Fx0/l0>, length=[0.5],
width=[0.02, relative], head_length=[0.1, relative],
color=red):
b2 := arrow( <x0,y0>, <-Fx0/l0,-Fy0/l0>,
length=[0.5],width=[0.02,relative], color=blue):

display(b0, b1, b2, scaling=CONSTRAINED);

          y0 := 0.4
          x0 := 0.9165151390
          Fx0 := 1.833030278
          Fy0 := 0.8
          l0 := 2.000000000

```



```
> ##### Exercise 7.
```

```
with(VectorCalculus):
```

```
SetCoordinates( 'cartesian' );
```

```
> ArcLength( <sin(t),sin(t)>, t=0..2*Pi ) ;
```

```
> SetCoordinates( 'cartesian' ):simplify(Curvature(
<sin(t),sin(t)> ))assuming t::real ;
```

$$4\sqrt{2}$$

$$0$$

```
>
```

```
> ##### Exercise 8.
```

```
#Hyperbole
```

```
> restart;F:=x^2-y^2-1;Fx:=diff(F, x);Fy:=diff(F, y);
y0:=1; x0:=sqrt(y0^2+1);
```

>

$$F := x^2 - y^2 - 1$$

$$Fx := 2x$$

$$Fy := -2y$$

$$y0 := 1$$

$$x0 := \sqrt{2}$$

>

```
with(plots):b0:=implicitplot(F=0, x=-2..2,y=-2..2,color=black ,
numpoints=1000):
```

```
#y0:=1; x0:=sqrt(y0^2+1);
```

```
Fx0:=eval( Fx, [x=x0, y=y0]);
```

```
Fy0:=eval( Fy, [x=x0, y=y0]);
```

```
l0:=(Fx0^2+Fy0^2)^(1/2);
```

```
b1 := arrow(<x0,y0>, <-Fy0/l0,Fx0/l0>, width=[0.02, relative],
head_length=[0.1, relative], color=red):
```

```
b2 := arrow( <x0,y0>, <-Fx0/l0,-Fy0/l0>,width=[0.02,relative],
color=blue):
```

```
display(b0, b1, b2, scaling=CONSTRAINED, axes=FRAMED);
```

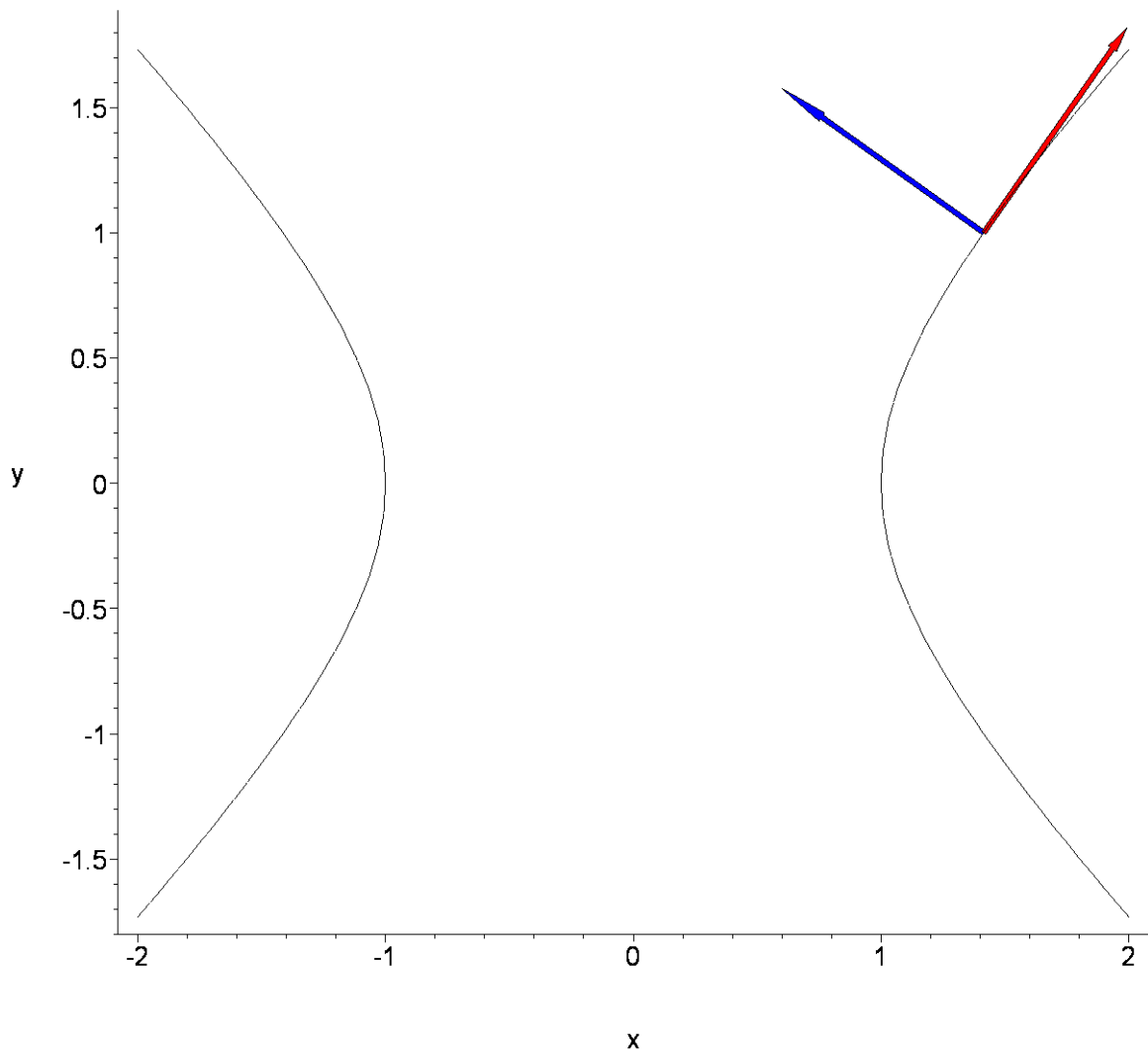
Warning, the name changecoords has been redefined

$$Fx0 := 2\sqrt{2}$$

$$Fy0 := -2$$

$$l0 := \sqrt{12}$$





> ##### Exercice 9

#Ellipse

> restart;F:=2\*x^2+3\*y^2-1;Fx:=diff(F, x);Fy:=diff(F, y);  
y0:=.1; solve(F,x)=0;x0:=max(eval(solve(F,x), y=y0));

>

$$F := 2x^2 + 3y^2 - 1$$

$$Fx := 4x$$

$$Fy := 6y$$

$$y0 := 0.1$$

$$\left( \frac{\sqrt{-6y^2 + 2}}{2}, -\frac{\sqrt{-6y^2 + 2}}{2} \right) = 0$$

$$x0 := 0.6964194140$$

>

with(plots):b0:=implicitplot(F=0, x=-2..2,y=-2..2,color=black ,  
numpoints=1000):

```

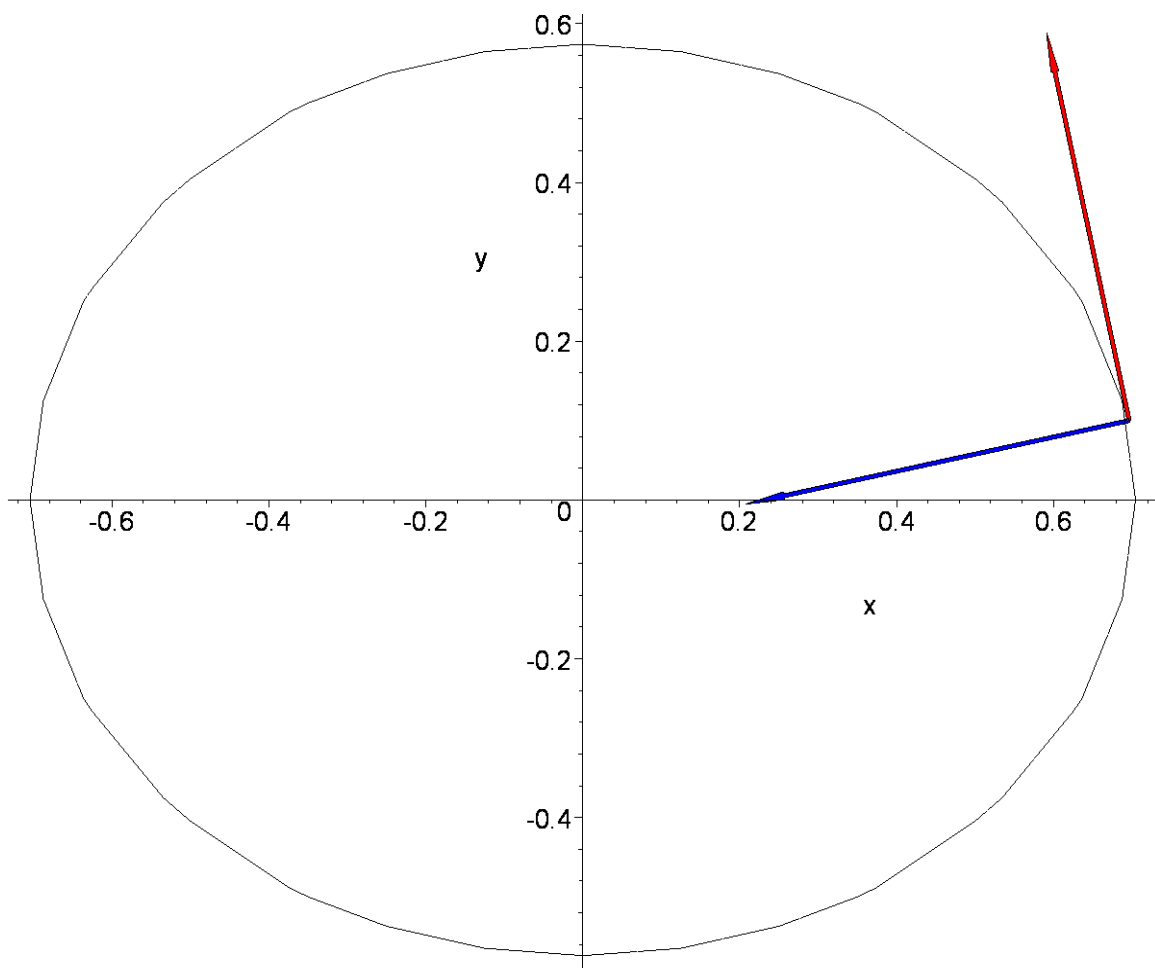
#y0:=1; x0:=sqrt(y0^2+1);
Fx0:=eval( Fx,[x=x0, y=y0]);
Fy0:=eval( Fy,[x=x0, y=y0]);
l0:=(Fx0^2+Fy0^2)^(1/2);
b1 := arrow(<x0,y0>, <-Fy0/l0,Fx0/l0>, length=[0.5],
width=[0.01, relative], head_length=[0.1, relative],
color=red):
b2 := arrow( <x0,y0>, <-Fx0/l0,-Fy0/l0>,
length=[0.5],width=[0.01, relative], head_length=[0.1,
relative], color=blue):
display(b0, b1, b2, scaling=CONSTRAINED, axes=NORMAL);

```

$Fx0 := 2.785677656$

$Fy0 := 0.6$

$l0 := 2.849561370$



[ >

[ > ##### Exercice 10

[ >

#Parabole

```
> restart;F:=y^2-6*x;Fx:=diff(F, x);Fy:=diff(F, y);
y0:=1; solve(F,x)=0;x0:=max(eval(solve(F,x), y=y0));
```

```
>
```

$$F := y^2 - 6x$$

$$Fx := -6$$

$$Fy := 2y$$

$$y0 := 1$$

$$\frac{y^2}{6} = 0$$

$$x0 := \frac{1}{6}$$

```
>
```

```
with(plots):
b0:=implicitplot(F=0, x=-2..2,y=-2..2,color=black ,
numpoints=1000,coords=cartesian):
#y0:=1; x0:=sqrt(y0^2+1);
Fx0:=eval( Fx, [x=x0, y=y0]);
Fy0:=eval( Fy, [x=x0, y=y0]);
l0:=(Fx0^2+Fy0^2)^(1/2);
b1 := arrow(<x0,y0>, <Fy0/l0,-Fx0/l0>, width=[0.01, relative],
head_length=[0.1, relative], color=red):
b2 := arrow( <x0,y0>, <Fx0/l0,Fy0/l0>,width=[0.01, relative],
head_length=[0.1, relative], color=blue):

display(b0, b1, b2, scaling=CONSTRAINED, axes=FRAMED);
```

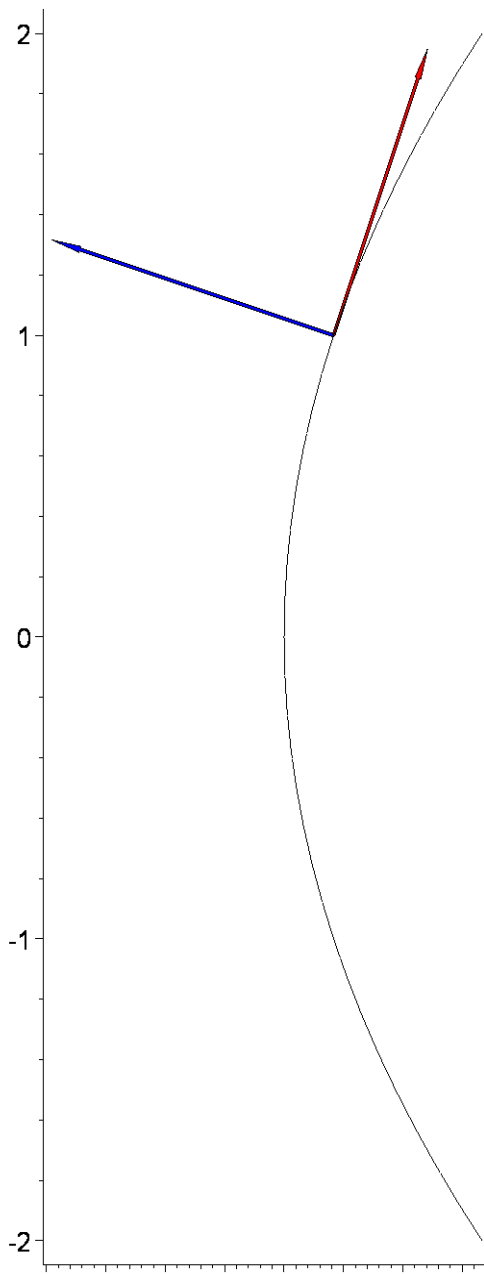
```
>
```

Warning, the name changecoords has been redefined

$$Fx0 := -6$$

$$Fy0 := 2$$

$$l0 := \sqrt{40}$$



>

```
#####
#Une courbe elliptique (cet exemple n'est pas inclus dans la
#feuille 3)
```

>

```
restart;F:=y^2-x^3+x;Fx:=diff(F, x);Fy:=diff(F, y);
x0:=-.1; solve(F,y)=0;y0:=max(eval(solve(F,y), x=x0));
```

>

```
F := y2 - x3 + x
Fx := -3x2 + 1
Fy := 2y
x0 := -0.1
(√(x3 - x), -√(x3 - x)) = 0
y0 := 0.3146426545
```

>

```
with(plots):b0:=implicitplot(F=0, x=-2..2,y=-2..2,color=black ,
numpoints=5000):
#y0:=1; x0:=sqrt(y0^2+1);
Fx0:=eval( Fx,[x=x0, y=y0]);
Fy0:=eval( Fy,[x=x0, y=y0]);
l0:=(Fx0^2+Fy0^2)^(1/2);
b1 := arrow(<x0,y0>, <-Fy0/l0,Fx0/l0>, width=[0.01, relative],
head_length=[0.1, relative], color=red):
b2 := arrow( <x0,y0>, <-Fx0/l0,-Fy0/l0>,width=[0.01, relative],
head_length=[0.1, relative], color=blue):

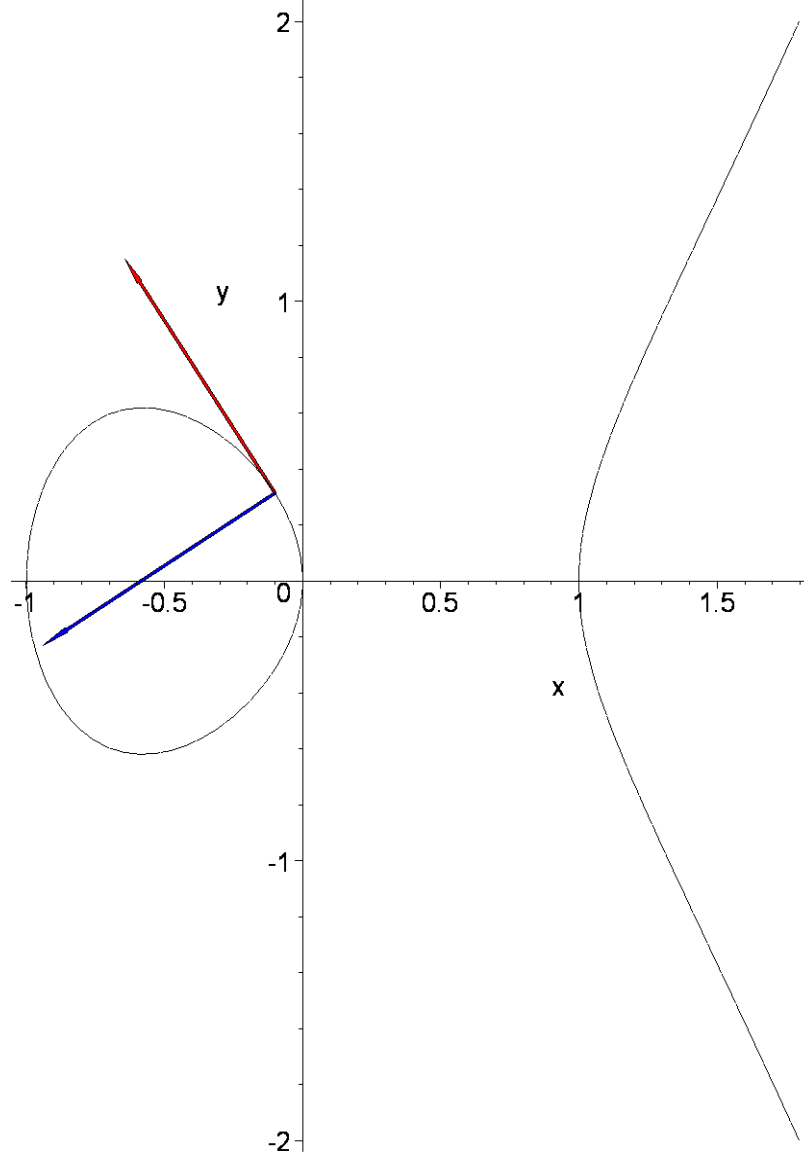
display(b0, b1, b2, scaling=CONSTRAINED);
```

Warning, the name changecoords has been redefined

$Fx0 := 0.97$

$Fy0 := 0.6292853090$

$l0 := 1.156243919$



> ##### Exercise 11

```
with(VectorCalculus):
SetCoordinates('cartesian');
K:=simplify(Curvature(<(1+cos(t)^2)*sin(t),sin(t)^2*cos(t)>))
assuming t::real;
```

Warning, the assigned names <,> and <|> now have a global binding

Warning, these protected names have been redefined and unprotected: \*, +, ., D, Vector, diff, int, limit, series

*cartesian*

$$K := \frac{1}{|3 \cos(t)^2 - 1|}$$

> R:=1/K;

$$R := |3 \cos(t)^2 - 1|$$

```
> x:=(1+cos(t)^2)*sin(t);y:=sin(t)^2*cos(t);
xp:=diff(x,t);yp:=diff(y,t);xs:=diff(xp,t);ys:=diff(yp,t);
```

$$x := (\cos(t)^2 + 1) \sin(t)$$

$$y := \sin(t)^2 \cos(t)$$

$$xp := -2 \sin(t)^2 \cos(t) + (\cos(t)^2 + 1) \cos(t)$$

$$yp := 2 \sin(t) \cos(t)^2 - \sin(t)^3$$

$$xs := -6 \sin(t) \cos(t)^2 + 2 \sin(t)^3 - (\cos(t)^2 + 1) \sin(t)$$

$$ys := 2 \cos(t)^3 - 7 \sin(t)^2 \cos(t)$$

```
> K:=simplify((xp*ys-yp*xs)/(xp^2+yp^2)^(3/2)) assuming t::real;
```

$$K := \frac{1}{|3 \cos(t)^2 - 1|}$$

```
> X:=simplify(x-(yp*(xp^2+yp^2))/(xp*ys-yp*xs));Y:=simplify(y+xp*(
xp^2+yp^2)/(xp*ys-yp*xs));
```

>

$$X := 2 \sin(t)^3$$

$$Y := 2 \cos(t)^3$$

> ##### Exercise 12

```
> with(VectorCalculus):
SetCoordinates('cartesian');
assume(t>0):K:=simplify(Curvature(<t-sinh(t)*cosh(t),2*cosh(t)>))
assuming t::real;
```

Warning, the assigned names <,> and <|> now have a global binding

Warning, these protected names have been redefined and unprotected: \*, +, ., D, Vector, diff, int, limit, series

*cartesian*

$$K := \frac{1}{2 \cosh(t)^2 \sinh(t)}$$

```

> R:=1/K;
      R := 2 cosh(t~)^2 sinh(t~)
> x:=t-sinh(t)*cosh(t);y:=2*cosh(t);
xp:=diff(x,t);yp:=diff(y,t);xs:=diff(xp,t);ys:=diff(yp,t);
      x := t~ - sinh(t~) cosh(t~)
      y := 2 cosh(t~)
      xp := 1 - cosh(t~)^2 - sinh(t~)^2
      yp := 2 sinh(t~)
      xs := -4 sinh(t~) cosh(t~)
      ys := 2 cosh(t~)
> K:=simplify((xp*ys-yp*xs)/(xp^2+yp^2)^(3/2)) assuming t::real;
      K :=  $\frac{1}{2} \frac{1}{\cosh(t~)^2 \sinh(t~)}$ 
> X:=simplify(x-(yp*(xp^2+yp^2))/(xp*ys-yp*xs));Y:=simplify(y+xp*(
xp^2+yp^2)/(xp*ys-yp*xs));
      X := -3 sinh(t~) cosh(t~) + t~
      Y := -2 cosh(t~) (cosh(t~)^2 - 2)
>
> #####
#####
> ##### Exercise 13
#####
r:=tan(t/2); x:=r*cos(t);y:=r*sin(t);r := tan(1/2*t);

      r := tan( $\frac{t~}{2}$ )
      x := tan( $\frac{t~}{2}$ ) cos(t~)
      y := tan( $\frac{t~}{2}$ ) sin(t~)
      r := tan( $\frac{t~}{2}$ )
> with(VectorCalculus):
SetCoordinates('polar');
K:=simplify(Curvature(<tan(t/2),t>)) assuming t::real;
      polar
      K := -  $\frac{(\cos(t~)^2 - \cos(t~) - 2)(\cos(t~) + 1)}{(-\cos(t~)^2 + 2)^{(3/2)}}$ 
> rp:=diff(r,t);rs:=diff(rp,t);
      rp :=  $\frac{1}{2} + \frac{1}{2} \tan^2\left(\frac{t~}{2}\right)$ 

```

$$rs := \tan\left(\frac{t\sim}{2}\right)\left(\frac{1}{2} + \frac{1}{2}\tan\left(\frac{t\sim}{2}\right)^2\right)$$

> `xp:=diff(x,t);yp:=diff(y,t);xs:=diff(xp,t);ys:=diff(yp,t);`

$$xp := \left(\frac{1}{2} + \frac{1}{2}\tan\left(\frac{t\sim}{2}\right)^2\right)\cos(t\sim) - \tan\left(\frac{t\sim}{2}\right)\sin(t\sim)$$

$$yp := \left(\frac{1}{2} + \frac{1}{2}\tan\left(\frac{t\sim}{2}\right)^2\right)\sin(t\sim) + \tan\left(\frac{t\sim}{2}\right)\cos(t\sim)$$

$$xs := \tan\left(\frac{t\sim}{2}\right)\left(\frac{1}{2} + \frac{1}{2}\tan\left(\frac{t\sim}{2}\right)^2\right)\cos(t\sim) - 2\left(\frac{1}{2} + \frac{1}{2}\tan\left(\frac{t\sim}{2}\right)^2\right)\sin(t\sim) - \tan\left(\frac{t\sim}{2}\right)\cos(t\sim)$$

$$ys := \tan\left(\frac{t\sim}{2}\right)\left(\frac{1}{2} + \frac{1}{2}\tan\left(\frac{t\sim}{2}\right)^2\right)\sin(t\sim) + 2\left(\frac{1}{2} + \frac{1}{2}\tan\left(\frac{t\sim}{2}\right)^2\right)\cos(t\sim) - \tan\left(\frac{t\sim}{2}\right)\sin(t\sim)$$

> `K:=simplify((xp*ys-yp*xs)/(xp^2+yp^2)^(3/2)) assuming t::real;`

$$K := \frac{(\cos(t\sim)^2 + 2 - 3\cos(t\sim))(\cos(t\sim) + 1)^3}{\sin(t\sim)^2(-\cos(t\sim)^2 + 2)^{(3/2)}}$$

> `X:=simplify(x-(yp*(xp^2+yp^2))/(xp*ys-yp*xs));Y:=simplify(y+xp*(xp^2+yp^2)/(xp*ys-yp*xs));`

$$X := -\frac{2\sin(t\sim)(-1 + \cos(t\sim))}{\cos(t\sim)^2 - \cos(t\sim) - 2}$$

$$Y := \frac{(2\cos(t\sim)^2 - 3)\cos(t\sim)}{\cos(t\sim)^3 - 3\cos(t\sim) - 2}$$

>

##### Exercise 14

`restart:print('(d/dt)*arcsin(sqrt(t))'=diff(arcsin(sqrt(t)),t));`

$$\frac{d \arcsin(\sqrt{t})}{dt} = \frac{1}{2\sqrt{t}\sqrt{1-t}}$$

> `print('(d/dt)*arcsin(sqrt(t))/(sqrt(t*(1-t)))'=diff((arcsin(sqrt(t)))/(sqrt(t*(1-t))),t));`

$$\frac{d \arcsin(\sqrt{t})}{dt \sqrt{t(1-t)}} = \frac{1}{2\sqrt{t}\sqrt{1-t}\sqrt{t(1-t)}} - \frac{1}{2} \frac{\arcsin(\sqrt{t})(1-2t)}{(t(1-t))^{(3/2)}}$$

> `simplify(diff((arcsin(sqrt(t)))/(sqrt(t*(1-t))),t));`

$$\frac{1}{2} \frac{-t^2 + t - \arcsin(\sqrt{t})\sqrt{t}\sqrt{1-t} + 2\arcsin(\sqrt{t})t^{(3/2)}\sqrt{1-t}}{t^{(3/2)}(1-t)^{(3/2)}\sqrt{-t(-1+t)}}$$

> `with(VectorCalculus):`

`SetCoordinates('cartesian');`

`print('arcsin(sqrt(t))/(sqrt(t*(1-t)))');`

`K:=simplify(Curvature(<t,(arcsin(sqrt(t)))/(sqrt(t*(1-t)))>));`



```
assuming t::positive :
```

```
Warning, the assigned names <, > and <|> now have a global binding
```

```
Warning, these protected names have been redefined and unprotected: *, +, ., D,  
Vector, diff, int, limit, series
```

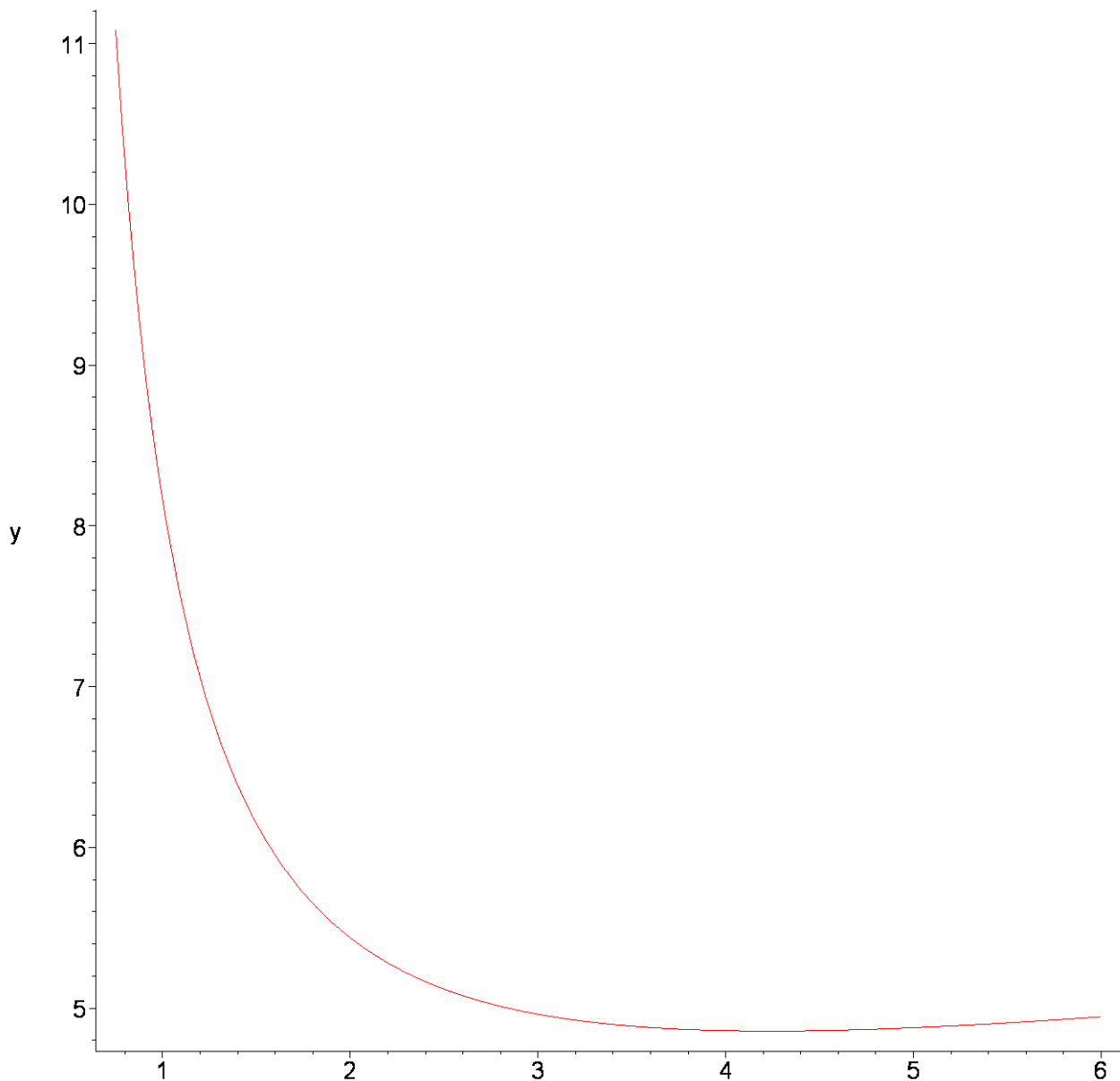
$$\frac{\text{cartesian} \arcsin(\sqrt{t})}{\sqrt{t(1-t)}}$$

```
> R:=1/K:
```

```
> ##### Exercise 15
```

```
restart;with(plots): plot([t^2+t, (t+1)*exp(1/t), t=0.5..2],  
labels=[x, y]);
```

```
Warning, the name changecoords has been redefined
```



>

```
with(VectorCalculus):
SetCoordinates('cartesian');
K:=simplify(Curvature(<t^2+t,(t+1)*exp(1/t)>)) assuming
t::positive:
```

Warning, the assigned names <, > and <|> now have a global binding

Warning, these protected names have been redefined and unprotected: \*, +, ., D, Vector, diff, int, limit, series

*cartesian*

>

```
##### Exercise 16
restart;P:=(x-y)/(x^2+y^2);Q:=(x+y)/(x^2+y^2);Py:=diff(P,y);
Qx:=diff(Q,x);'Py'-'Qx'=simplify(Py-Qx);F:=int(P,x);'Q'=simplify
(diff(int(P,x),y));
```

$$P := \frac{x-y}{x^2+y^2}$$

$$Q := \frac{x+y}{x^2+y^2}$$

$$Py := -\frac{1}{x^2+y^2} - \frac{2(x-y)y}{(x^2+y^2)^2}$$

$$Qx := \frac{1}{x^2+y^2} - \frac{2(x+y)x}{(x^2+y^2)^2}$$

$$Py - Qx = 0$$

$$F := \frac{1}{2} \ln(x^2+y^2) - \arctan\left(\frac{x}{y}\right)$$

$$Q = \frac{x+y}{x^2+y^2}$$

```
> assume( a > 0 );
FP1:=evala(subs({x=a, y=-a},F));
FP2moins:=evala(limit((subs({x=a},F), y=0, left)));
FP2plus:=evala(limit((subs({x=a},F), y=0, right)));
FP3moins:=evala(limit((subs({x=a},F), y=0, right)));
FP3plus:=evala(limit((subs({x=a},F), y=0, left)));
```

$$FP1 := \frac{1}{2} \ln(2a^2) + \frac{\pi}{4}$$

$$FP2moins := \ln(a) + \frac{\pi}{2}$$

$$FP2plus := \ln(a) - \frac{\pi}{2}$$

$$FP3moins := \ln(a) - \frac{\pi}{2}$$

$$FP3plus := \ln(a) + \frac{\pi}{2}$$

```
> print(' (F(P[2,moins]) - F(P[1])) + F(P[3,plus]) - F(P[2,plus]) + (F(P[1])
) - F(P[3,moins])) '
=FP2moins-FP1+FP3plus-FP2plus+FP1-FP3moins);
```

$$F(P_{2,moins}) - F(P_1) + F(P_{3,plus}) - F(P_{2,plus}) + F(P_1) - F(P_{3,moins}) = 2\pi$$

```
> x:=a*cos(t);y:=a*sin(t);
print('P*diff(x,t)+Q*diff(y,t)'=P*diff(x,t)+Q*diff(y,t));
simplify(P*diff(x,t)+Q*diff(y,t));
```

$$x := a \cos(t)$$

$$y := a \sin(t)$$

$$P\left(\frac{\partial}{\partial t}x\right)+Q\left(\frac{\partial}{\partial t}y\right)=-\frac{(a\cos(t)-a\sin(t))a\sin(t)}{a^2\cos(t)^2+a^2\sin(t)^2}+\frac{(a\cos(t)+a\sin(t))a\cos(t)}{a^2\cos(t)^2+a^2\sin(t)^2}$$

```
> print('int(1,t=0..2*Pi)'=int(1,t=0..2*Pi));
```

$$\int_0^{2\pi} 1 dt = 2\pi$$

```
> ##### Exercice 17
```

```
> restart;P:=exp(x)*cos(y)+x*y^2;Q:=(-exp(x)*sin(y)+x^2*y);
```

$$P := e^x \cos(y) + x y^2$$

$$Q := -e^x \sin(y) + x^2 y$$

```
> diff(P,y);
```

```
diff(Q,x);
```

$$-e^x \sin(y) + 2xy$$

$$-e^x \sin(y) + 2xy$$

```
> F:=exp(x)*cos(y)+x^2*y^2/2;'P'=diff(F,x);'Q'=diff(F,y);
```

$$F := e^x \cos(y) + \frac{x^2 y^2}{2}$$

$$P = e^x \cos(y) + x y^2$$

$$Q = -e^x \sin(y) + x^2 y$$

```
> int(P,x);
```

$$e^x \cos(y) + \frac{x^2 y^2}{2}$$

```
> #Soit a;b > 0. Calculer int( x^2*dy + y^2*dx, o u a pour
equation cart esienne l'une des
```

```
# equations suivantes: x^2 + y^2 - a*x=0; (x/a)^2 + (y/b)^2=1;
```

```
# (x/a)^2 + (y/b)^2 - 2*(x/a) - 2*(y/b)=0;
```

```
> assume(a>0);assume(b>0);
```

```
> x:=(a/2)*(cos(t)+1);y:=(a/2)*(sin(t));
```

$$x := \frac{1}{2} a (\cos(t) + 1)$$

$$y := \frac{1}{2} a \sin(t)$$

```
> xp:=diff(x,t);yp:=diff(y,t);
```

$$xp := -\frac{1}{2} a \sin(t)$$

$$yp := \frac{1}{2} a \cos(t)$$

```
> x^2*yp+y^2*xp;
```

$$a^2 (\sqrt{2} \cos(t) + 1)^2 b \sqrt{2} \cos(t) - b^2 (\sqrt{2} \sin(t) + 1)^2 a \sqrt{2} \sin(t)$$

```

> simplify(int(x^2*yp+y^2*xp,t));
>

$$\frac{1}{24} a^3 (\cos(t)^2 \sin(t) + 3 \sin(t) \cos(t) + 5 \sin(t) + 3 t - \cos(t)^3 + 3 \cos(t))$$

> x^2*yp+y^2*xp;

$$\frac{1}{8} a^3 (\cos(t) + 1)^2 \cos(t) - \frac{1}{8} a^3 \sin(t)^3$$

> simplify(int(x^2*yp+y^2*xp,t=0..2*Pi));

$$\frac{a^3 \pi}{4}$$

> #####
x:=a*(cos(t));y:=(b)*(sin(t));

$$x := a \cos(t)$$


$$y := b \sin(t)$$

> xp:=diff(x,t);yp:=diff(y,t);

$$xp := -a \sin(t)$$


$$yp := b \cos(t)$$

> simplify(int(x^2*yp+y^2*xp,t));
>

$$\frac{1}{3} a b (a \cos(t)^2 \sin(t) + 2 a \sin(t) + 3 b \cos(t) - b \cos(t)^3)$$

> x^2*yp+y^2*xp;

$$a^2 \cos(t)^3 b - b^2 \sin(t)^3 a$$

> simplify(int(x^2*yp+y^2*xp,t=0..2*Pi));
0
> #####
restart;P:=y^2;Q:=x^2;

$$P := y^2$$


$$Q := x^2$$

> diff(P,y);
diff(Q,x);

$$2 y$$


$$2 x$$

> #####
> restart;((x/a)-1)^2+((y/b)-1)^2=2;

$$\left(\frac{x}{a} - 1\right)^2 + \left(\frac{y}{b} - 1\right)^2 = 2$$

> x:=a*(sqrt(2)*cos(t)+1);y:=(b)*(sqrt(2)*sin(t)+1);

$$x := a(\sqrt{2} \cos(t) + 1)$$


$$y := b(\sqrt{2} \sin(t) + 1)$$

> xp:=diff(x,t);yp:=diff(y,t);

```

$$xp := -a\sqrt{2} \sin(t)$$

$$yp := b\sqrt{2} \cos(t)$$

```
> simplify(int(x^2*yp+y^2*xp,t));
```

```
>
```

$$\frac{1}{3}ab(2a\cos(t)^2\sin(t)\sqrt{2} + 6a\cos(t)\sin(t) + 7a\sqrt{2}\sin(t) + 6b\sin(t)\cos(t) - 6bt + 9b\sqrt{2}\cos(t) + 6at - 2b\sqrt{2}\cos(t)^3)$$

```
> x^2*yp+y^2*xp;
```

$$a^2(\sqrt{2}\cos(t)+1)^2b\sqrt{2}\cos(t) - b^2(\sqrt{2}\sin(t)+1)^2a\sqrt{2}\sin(t)$$

```
> simplify(int(x^2*yp+y^2*xp,t));
```

$$\frac{1}{3}ab(2a\cos(t)^2\sin(t)\sqrt{2} + 6a\cos(t)\sin(t) + 7a\sqrt{2}\sin(t) + 6b\sin(t)\cos(t) - 6bt + 9b\sqrt{2}\cos(t) + 6at - 2b\sqrt{2}\cos(t)^3)$$

```
> simplify(int(x^2*yp+y^2*xp,t=0..2*Pi));
```

$$4a^2b\pi - 4ab^2\pi$$

```
>
```