

*Donaldson-Tian-Yau's Conjecture
for general polarization*

Toshiki Mabuchi, Osaka University

Ricci curvature: limit spaces and Kähler geometry

ICMS, Edinburgh, Scotland, UK

Table of Contents

1. *Introduction*

2. *Background materials*

- The Donaldson-Futaki invariant F_1 for test configurations
- K-stability and Li-Xu's pathology in Donaldson-Tian-Yau's Conjecture
- Characterization of F_1 and the Chow weight in terms of the Chow norm

3. *The Donaldson-Futaki invariant F_1 is generalized to f_1*

- f_1 is defined on the set \mathcal{M} of all sequences of test configurations.

4. *Strong K-stabilities*

- Li-Xu's pathology doesn't occur in the strong version of K-stability.
- Strong K-stability implies asymptotic Chow-stability.

5. *Existence of CSC Kähler metrics*

- An outline of our approach

6. *Concluding Remarks*

1. *Introduction*

Setting-up: (X,L) : a polarized algebraic manifold, i.e.,

X : non-singular irreducible algebraic variety

L : very ample line bundle on X

In this talk, Donaldson-Tian-Yau's Conjecture for general polarization will be considered:

Conjecture: If (X,L) is strongly K-stable, then the polarization class $c_1(L)$ admits a CSC Kähler metric.

2. Background Materials

A test configuration $(\mathcal{X}, \mathcal{L}, \varphi)$ for (X, L)

Let $\mathcal{X} \subset \mathbf{C} \times \mathbf{P}^*(V)$ be a \mathbf{C}^* -invariant subset for the \mathbf{C}^* -action

$$\mathbf{C}^* \times (\mathbf{C} \times \mathbf{P}^*(V)) \ni (t, (z, p)) \rightarrow (tz, \varphi(t)p),$$

for a 1-PS $\varphi: \mathbf{C}^* \rightarrow \mathrm{SL}(V)$, where $\mathrm{SL}(V)$ acts naturally on the set $\mathbf{P}^*(V)$ of all hyperplanes in V passing through the origin, and we usually take $V = V_l = \Gamma(X, L^l)$ assuming that V has a natural metric structure such that $S^1 \subset \mathbf{C}^*$ acts isometrically on V .

A triple $(\mathcal{X}, \mathcal{L}, \varphi)$ is called a *test configuration* for (X, L) if

- (1) \mathcal{L} is the restriction to \mathcal{X} of the pullback $\mathrm{pr}_2^* \mathcal{O}_{\mathbf{P}^*(V)}(1)$ of the hyperplane bundle on $\mathbf{P}^*(V)$ on which \mathbf{C}^* acts naturally;
- (2) $(\mathcal{X}_t, \mathcal{L}_t) \cong (X, L^l)$, $t \neq 0$,

for some positive integer l independent of the choice of t .

This l is called the *exponent* of the test configuration $\mu = (\mathcal{X}, \mathcal{L}, \varphi)$.

The Chow norm on W_k by Zhang

$d(k) :=$ degree of X in $\mathbf{P}^*(V_k)$ embedded by $|L^m|$, where
 $V_k := \Gamma(X, L^m)$, $m = kl$, $n = \dim X$, $W_k := \{S^{d(k)}(V_k)^*\}^{\otimes n+1}$.
Let $0 \neq \text{CH}_k(X) \in W_k$ be the Chow form for the
irreducible reduced algebraic cycle X on $\mathbf{P}^*(V_k)$,
so that $[\text{CH}_k(X)] \in \mathbf{P}(W_k)$ is the Chow point for the
cycle X . Consider the ***Chow norm*** $\| \cdot \| : W_k \rightarrow \mathbf{R}$,

$$0 \leq \|w\| \in \mathbf{R}, \quad w \in W_k.$$

The Donaldson-Futaki invariant

$$F_1 = F_1(\mu) \text{ for } \mu = (\mathcal{X}, \mathcal{L}, \varphi)$$

- $N_k := \dim \Gamma(X, L^k) = \dim \Gamma(\mathcal{X}_0, \mathcal{L}_0^m)$, where $k = l m$.
- $w_k :=$ weight of the \mathbf{C}^* -action on $\det \Gamma(\mathcal{X}_0, \mathcal{L}_0^m)$

$$\begin{aligned} & w_k / (k N_k) \quad (k \gg 1) \\ & = F_0(\mu) + F_1(\mu) k^{-1} + F_2(\mu) k^{-2} + \dots \end{aligned}$$

$F_1 = F_1(\mu)$ is called the *Donaldson-Futaki invariant* for test configuration $\mu = (\mathcal{X}, \mathcal{L}, \varphi)$ of (X, L) .

K-stability and Li-Xu's pathology

- A test configuration $\mu = (\mathcal{X}, \mathcal{L}, \varphi)$ for (X, L) is called *trivial* if φ is trivial.
- (X, L) is called *K-stable* if the following conditions are satisfied:
 - (1) $F_1(\mu) \leq 0$ for all test configurations $\mu = (\mathcal{X}, \mathcal{L}, \varphi)$ for (X, L) .
 - (2) If $F_1(\mu) = 0$, then the normalization test configuration of μ is trivial.
- In the original definition of K-stability by Donaldson, (2) is stated as “If $F_1(\mu) = 0$, then μ is trivial.” However, Li-Xu gave an example of a nontrivial test configuration $\mu = (\mathcal{X}, \mathcal{L}, \varphi)$ for $(\mathbf{P}^1, \mathcal{O}_{\mathbf{P}^1}(3))$ such that $F_1(\mu)$ vanishes, and that the normalization of μ is trivial. Hence the definition of K-stability is reformulated as above.

Characterization of F_1 and the Chow weight in terms of the Chow norm

For a test configuration $\mu = (\mathcal{X}, \mathcal{L}, \varphi)$, we consider the homogeneous ideal $I = \bigoplus_m I_m$ for \mathcal{X}_0 in $\mathbf{P}^*(V)$, where $V := V_l$. For $k = l, m$, we put

$$V_k = S^m(V) / I_m, \quad m = 1, 2, \dots,$$

where $S^k(V)$ denotes the k -th symmetric tensor product of V .

Then $\varphi: \mathbf{C}^* \rightarrow \mathrm{SL}(V)$ induces a representation $\varphi_k: \mathbf{C}^* \rightarrow \mathrm{GL}(V_k)$.

For its special linear form $\varphi_k^{\mathrm{SL}}: \mathbf{C}^* \rightarrow \mathrm{SL}(V_k)$ (modulo finite group), by using the Chow norm $\|\cdot\|$, we set

$$v_k(s) := \log \|\varphi_k^{\mathrm{SL}}(\exp(s)) \cdot \mathrm{CH}_k(X)\|,$$

Let q_k be the (possibly rational) Chow weight of the \mathbf{C}^* -action by φ_k^{SL} on the line $\mathbf{C} \cdot \mathrm{CH}_k(\mathcal{X}_0)$. Then by writing $F_i(\mu)$ as F_i shortly, we obtain

$$q_k = \lim_{s \rightarrow -\infty} dv_k(s)/ds = (n+1)! c_1(L)^n[X] (F_1 k^n + F_2 k^{n-1} + F_3 k^{n-2} + \dots).$$

**3. *The Donaldson-Futaki invariant F_1
is generalized to f_1***

Norms for the the infinitesimal generator u

For a test configuration $\mu = (\mathcal{X}, \mathcal{L}, \varphi)$, we consider the infinitesimal generator u of φ satisfying $\exp(2\pi u \sqrt{-1}) = \text{id}_V$, so that

$$\varphi(\exp s) = \exp(su), \quad s \in \mathbf{C}.$$

Then φ is called the 1-PS generated by u , and is written as φ_u . Let b_1, b_2, \dots, b_N be the weights of the \mathbf{C}^* -action for φ , so that each $\varphi(t)$, $t \in \mathbf{C}^*$, is written as a diagonal matrix with the γ -th diagonal elements t^{b_γ} , $\gamma=1,2,\dots, N$. Let n be the dimension of X , and l be the exponent of the test configuration $\mu = (\mathcal{X}, \mathcal{L}, \varphi)$. Define

$$\begin{aligned} |u|_1 &:= l^{-n-1} (|b_1| + |b_2| + \dots + |b_N|), \\ |u|_\infty &:= l^{-1} \max\{|b_1|, |b_2|, \dots, |b_N|\}. \end{aligned}$$

Definition of $f_1: \mathcal{M} \rightarrow \mathbf{R} \cup \{-\infty\}$

Consider a sequence $\{\mu_j\}$ of test configurations $\mu_j = (\mathcal{X}_j, \mathcal{L}_j, \varphi_j)$ such that the exponent l_j of μ_j satisfies $l_j \rightarrow +\infty$ as $j \rightarrow \infty$.

Let \mathcal{M} be the set of all such sequences $\{\mu_j\}$. For $s \in \mathbf{R}$, we define

$$\begin{aligned} v_j(s) &:= (|u_j|_\infty / |u_j|_1) l_j^{-n} \log \|\varphi_j(t) \cdot \text{CH}_j(X)\| \\ &= (|u_j|_\infty / |u_j|_1) l_j^{-n} \log \|\exp(su_j / |u_j|_\infty) \cdot \text{CH}_j(X)\|, \end{aligned}$$

where $t = \exp(s/|u_j|_\infty)$. We can then define

$$f_1(\{\mu_j\}) := \lim_{s \rightarrow -\infty} \underline{\lim}_{j \rightarrow \infty} dv_j/ds.$$

If the double limit commutes and if $\lim_{j \rightarrow \infty} |u_j|_1$ exists as a positive real number $r > 0$, then by characterization of F_1 in terms of the Chow norm, we obtain (compare this with Szekelyhidi's approach)

$$f_1(\{\mu_j\}) = r^{-1}(n+1)! c_1(L)^n [X] \underline{\lim}_{j \rightarrow \infty} F(\mu_j).$$

Some remark on f_1

For instance, for a test configuration $\mu = (\mathcal{X}, \mathcal{L}, \varphi)$ for (X, L) of exponent 1, let $\mu_j = (\mathcal{X}_j, \mathcal{L}_j, \varphi_j)$, $j = 1, 2, \dots$, be the test configurations such that

$$\mathcal{X}_j = \mathcal{X}, \quad \mathcal{L}_j = \mathcal{L}^j$$

and that $\varphi_j: \mathbf{C}^* \rightarrow \mathrm{SL}(V_j)$ is induced by $\varphi: \mathbf{C}^* \rightarrow \mathrm{SL}(V)$, where $V_j := \Gamma(\mathcal{X}_0, \mathcal{L}_0^j)$ and $V := \Gamma(\mathcal{X}_0, \mathcal{L}_0)$. Replacing $\{\mu_j\}$ by its subsequence if necessary, we may assume that $r = \lim_{j \rightarrow \infty} |u_j|_1 \geq 0$ exists.

For this sequence, if $r > 0$, then the double limit commutes, so that

$$f_1(\{\mu_j\}) = r^{-1}(n+1)! c_1(L)^n [X] F_1(\mu).$$

Note that, for the test configuration in Li-Xu's pathology, $r = 0$.

4. *Stabilities*

Asymptotic Chow-stability

Let $G_k := \mathrm{SL}(V_k)$ which naturally acts on V_k and also on W_k .
For the Chow form $\mathrm{CH}_k(X)$ for $X \subset \mathbf{P}^*(V_k)$, we consider its orbit
 $G_k \cdot \mathrm{CH}_k(X)$ in W_k .

Definition: (1) (X, L^k) is called ***Chow-stable***, if $G_k \cdot \mathrm{CH}_k(X)$ is closed
in W_k and the isotropy subgroup of G_k at $\mathrm{CH}_k(X)$ is finite.

(2) (X, L) is called ***asymptotically Chow-stable***, if for all $k \gg 1$,
 (X, L^k) is Chow-stable.

Hilbert-Mumford stability criterion

Definition: (1) Fix a Hermitian metric ρ_k on V_k . We define $(\mathfrak{sl}_k)_{\mathbf{Z}}$ as the set of all $u \in \mathfrak{sl}(V_k)$ such that $\exp(2\pi\sqrt{-1}u) = 1_{V_k}$ and that the circle group $\exp(2\pi\sqrt{-1}su)$, $s \in \mathbf{R}$, acts isometrically on (V_k, ρ_k) .
(2) For each $u \in \mathfrak{sl}(V_k)$, let G_u denote the 1-dimensional algebraic torus in $\mathrm{SL}(V_k)$ generated by u .

Then by the Hilbert-Mumford stability criterion, in order to show the closedness of $G_k \cdot \mathrm{CH}_k(X)$ in W_k , it suffices to show the closedness of the orbit $G_u \cdot \mathrm{CH}_k(X)$ in W_k for all $0 \neq u \in (\mathfrak{sl}_k)_{\mathbf{Z}}$, i.e., suffices to show that the Chow weight $q(u)$ at $\lim_{s \rightarrow -\infty} \exp(2\pi\sqrt{-1}su) \cdot \mathrm{CH}_k(X)$ is negative for all $0 \neq u \in (\mathfrak{sl}_k)_{\mathbf{Z}}$.

Strong K-stability

For each $u \in (\mathfrak{sl}_k)_{\mathbb{Z}}$, we consider the 1-PS $\varphi_u: \mathbb{C}^* \rightarrow \mathrm{SL}(V_k)$ generated by u , and let $(\mathcal{X}^u, \mathcal{L}^u, \varphi_u)$ be the associated test configuration obtained as the DeContini Procesi family.

Let \mathcal{M} be the set of all sequences $\mu_j = (\mathcal{X}^{u_j}, \mathcal{L}^{u_j}, \varphi_{u_j})$, $j = 1, 2, \dots$, of test configurations for (X, L) such that $u_j \in (\mathfrak{sl}_k)_{\mathbb{Z}}$, and that the exponent l_j of μ_j satisfies $l_j \rightarrow +\infty$ as $j \rightarrow \infty$.

Definition: (1) (X, L) is **strongly K-semistable**, if $f_1(\{\mu_j\}) \leq 0$ for all $\{\mu_j\} \in \mathcal{M}$.

(2) Let (X, L) be strongly K-semistable. Then (X, L) is called **strongly K-stable**, if the equality $f_1(\{\mu_j\}) = 0$ for $\{\mu_j\} \in \mathcal{M}$ implies that there exists a j_0 such that μ_j is trivial for all j satisfying $j \geq j_0$.

Strong K-stability and Li-Xu's pathology

Li-Xu's pathology doesn't occur in our new definition of f_1 .
Actually, for their example of a test configuration, we have $f_1 = -\infty$
(see arXiv: 1305.6411). Hence the following conjecture in the
introduction is proposed:

Conjecture: If (X,L) is strongly K-stable, then the polarization class $c_1(L)$ admits a CSC Kähler metric.

Strong K-stability implies asymptotic Chow-stability

Our strong K-stability concept seems to be natural in the sense that we have the following result (“*Strong K-stability and asymptotic Chow-stability*”, joint work with Y. Nitta, arXiv: 1307.1959):

Theorem: *If (X,L) is strongly K-stable, then (X,L) is asymptotically Chow-stable.*

Outline of proof for the Theorem

We here explain how, for $l \gg 1$, the Chow weight $q(u)$ is shown to satisfy: $q(u) < 0$ for all $0 \neq u \in (\mathbf{s}\mathbf{1}_l)_\mathbb{Z}$. Assume, for contradiction, that there exists a sequence

$$l_1 < l_2 < \dots < l_j < \dots$$

with $0 \neq u_j \in (\mathbf{s}\mathbf{1}_{l_j})_\mathbb{Z}$ such that $q(u_j) \geq 0$ for all positive integers j .

Now we consider the test configurations

$$(\mathcal{X}_j, \mathcal{L}_j, \varphi_j), \quad j = 1, 2, \dots,$$

associated to u_j above. By the characterization of F_1 and the Chow weight in terms of the Chow norm, we obtain

$$0 \leq l_j^{-n} |u_j|_1^{-1} q(u_j) = \lim_{s \rightarrow -\infty} dv_j(s)/ds$$

By convexity of the function v_j , we have $dv_j(s)/ds \geq 0$ on $-\infty < s < -\infty$.

Then by taking $\lim_{s \rightarrow -\infty} \lim_{j \rightarrow \infty}$, we obtain $f_1(\{\mu_j\}) \geq 0$. Hence by strong K-stability, it follows that $f_1(\{\mu_j\}) = 0$ and μ_j is trivial for $j \gg 1$.

This is a contradiction to the fact that $u_j \neq 0$ for all j .

5. Existence of CSC Kähler metrics

Geometry of Hermitian metrics on a complex vector space V

Let ρ_1, ρ_2 be Hermitian metrics on a vector space V . Then for a suitable orthonormal basis (e_1, e_2, \dots, e_N) for (V, ρ_1) , we can write

$$\begin{aligned}\rho_2(e_\alpha, e_\beta) &= 0, & \alpha \neq \beta, \\ \rho_2(e_\alpha, e_\alpha) &= \lambda_\alpha, & \alpha = 1, 2, \dots, N,\end{aligned}$$

where λ_α are positive real numbers. Replacing ρ_2 by its positive constant multiple, we may assume that $\prod_\alpha \lambda_\alpha = 1$. Put $b_\alpha = \log \sqrt{\lambda_\alpha}$. Then the 1-PS $\varphi(\exp s) = \sum_\alpha \exp(b_\alpha s) e_\alpha \otimes e_\alpha^*$ from \mathbf{R}_+ to $\mathrm{SL}(V)$ interpolates ρ_1 and ρ_2 in the sense that $\varphi(\exp s) \cdot \rho_1$ is ρ_1 or ρ_2 according as $s = 0$ or $s = 1$.

The (multiplicative) **C^0 -distance** $d(\rho_1, \rho_2)$ between ρ_1 and ρ_2 is defined as

$$d(\rho_1, \rho_2) = C \max\{|b_\alpha|; \alpha = 1, 2, \dots, N\},$$

where C is a positive real constant depending only on V . We often reparametrize $\varphi(\exp s)$ by replacing s by $d(\rho_1, \rho_2)^{-1}s$. Namely,

$\varphi(\exp s) = \sum_\alpha \exp(b_\alpha d(\rho_1, \rho_2)^{-1}s) e_\alpha \otimes e_\alpha^*$ is **C^0 -distance parametrized** in the sense that $\varphi(\exp s) \cdot \rho_1$ is ρ_1 or ρ_2 according as $s = 0$ or $s = d(\rho_1, \rho_2)$.

An outline of our approach (I)

Assume that (X,L) is strongly K-stable relative to T . By the joint work with Nitta, (X,L) is asymptotically Chow-stable. Then replacing L by its positive integral multiple, we may assume that (X,L_j) are Chow-stable for all positive integers j . Hence we have a sequence of balanced metrics ω_j in the sense that it is a critical point of the Chow norm satisfying $B_j(\omega_j) = \text{constant}$.

Fix a Hermitian metric h on L such that $\omega = c_1(L,h)$ is Kähler.

Let $\omega_j = c_1(L,h_j)$ be a balanced metric. Then $V_j = H^0(X, L_j)$ has Hermitian metrics ρ_1 and ρ_j defined by

$$\rho_1(\tau, \tau') = \int_X (\tau, \tau')_h \omega^n \quad \text{and} \quad \rho_j(\tau, \tau') = \int_X (\tau, \tau')_{h_j} \omega_j^n,$$

for $\tau, \tau' \in V_j$. We then have the interpolation of ρ_1 and ρ_2 by a 1-PS φ_j of $\text{SL}(V_j)$, where replacing s by $d(\rho_1, \rho_2)^{-1}s$, we may assume that φ_j is C^0 -distance parametrized.

An outline of our approach (II)

• If $\beta_j = (b_1, b_2, \dots, b_{N_j})$ is a rational vector, then 1-PS φ_j comes from a C^* -action. If not, approximating β_j by a sequence of rational vectors, we may assume that β_j is a rational vector.

• Since the Chow norm is critical at balanced metrics, we have

$dv_j(s)/ds = 0$ at s corresponding to the Chow norm, i.e., at $s = -d(\rho_1, \rho_j)$.

• Then we consider the sequence of test configurations $\mu_j = (\mathcal{X}_j, \mathcal{L}_j, \varphi_j)$

associated to φ_j .

Put $d_\infty = \sup_j d(\rho_1, \rho_j)$

Then the following two cases are possible:

(Case 1) $d_\infty < +\infty$.

(Case 2) $d_\infty = +\infty$.

An outline of our approach (III)

- If Case 1 occurs, then the C^0 -distances $d(\rho_1, \rho_j)$ are uniformly bounded from above, and hence it is not difficult to show that a suitable subsequence of the balanced Kähler metrics $\omega_j, j = 1, 2, \dots$, converges to a CSC Kähler metric.

- If Case 2 occurs, replacing $\{\omega_j\}$ by its subsequence if necessary, we may assume that the sequence $d(\rho_1, \rho_j), j = 1, 2, \dots$, is monotone-increasing (to $+\infty$), as $j \rightarrow \infty$.

Note that $dv_j(s)/ds = 0$ at $s = -d(\rho_1, \rho_j)$. Then for every j' with $j' \geq j$, since $dv_{j'}(s)/ds$ is non-decreasing in s ,

$$0 = dv_{j'}(s)/ds|_{s=-d(\rho_1, \rho_{j'})} \leq dv_{j'}(s)/ds|_{s=-d(\rho_1, \rho_j)}$$

Hence the non-decreasing function $\lim_{j' \rightarrow \infty} dv_{j'}(s)/ds$ satisfies ≥ 0 on the interval $-d(\rho_1, \rho_j) \leq s$. Since $d(\rho_1, \rho_j) \rightarrow +\infty$ as $j \rightarrow \infty$, it now follows that

$\lim_{j' \rightarrow \infty} dv_{j'}(s)/ds \geq 0$ on the whole real line $-\infty < s < +\infty$. Then

$f_1(\{\mu_j\}) = \lim_{s \rightarrow -\infty} \lim_{j' \rightarrow \infty} dv_{j'}(s)/ds \geq 0$. Now by strong K-stability of (X, L) , $f_1(\{\mu_j\}) = 0$ and μ_j are trivial for $j \gg 1$.

Thus $\{\omega_j\}$ converges to a CSC Kähler metric.

6. *Concluding remarks*

Why strong K-stability ?

E : irreducible holomorphic vector bundle over a compact Kähler manifold (M, ω)

$\mu(\mathcal{S}) := \text{deg}(\mathcal{S})/\text{rk}(\mathcal{S})$ for \mathcal{S} below.

E is stable (in the sense of Mumford-Takemoto)

$\Leftrightarrow \mu(\mathcal{S}) < \mu(E) \quad \forall$ coherent subsheaf \mathcal{S} of $\mathcal{O}(E)$
with $0 < \text{rk}(\mathcal{S}) < \text{rk}(E)$

Remark: If $\dim_{\mathbb{C}} M = 1$, then \mathcal{S} can be chosen as a vector subbundle of E .

Hitchin-Kobayashi correspondence (Narasimhan-Seshadri, Kobayashi, Lübke, Donaldson, Uhlenbeck-Yau):

E is stable $\Leftrightarrow \exists$ Hermitian-Einstein metric on E

Manifolds case versus vector bundles case in the Hitchin-Kobayashi correspondence

vector bundles

holomorphic vector bundles

vector subbundles

rank of a vector subbundle

coherent subsheaf

slope $\nu(\mathcal{S}) = \text{deg}(\mathcal{S})/\text{rk}(\mathcal{S})$

$$\nu(\mathcal{S}) \leq \nu(E)$$

the Mumford-Takemoto stability

compact Riemann surfaces case

manifolds

polarized algebraic manifolds

test configurations

exponent of a test configuration

?

the Donaldson-Futaki invariant

$$F_1(\mu) \leq 0$$

(strong) K-stability

Kähler-Einstein case

This indicates the necessity of considering a suitable compactification \mathcal{M} of the moduli space of test configurations for (X,L) .

K-stability versus strong K-stability

Recent results by Tian and Chen-Donaldson-Sun show that K-stability is equivalent (up to Li-Xu's pathology) to strong K-stability for Kähler-Einstein case, i.e., for anti-canonical polarization. Donaldson's result for toric case shows also that these two stability concepts coincide for toric case.

However, for general polarization L on a general X , the graded \mathbf{C} -algebra associated to the limit μ_∞ in the compactified moduli space \mathcal{M} is not finitely generated in general. Hence we proposed the concept of strong K-stability.

Extremal Kähler case

By taking a maximal algebraic torus T in $\text{Aut}(X)$, we see that the arguments above is valid not only for non-discrete automorphisms cases but also for extremal Kähler cases.

For extremal Kähler cases,

(1) balanced metrics, the Chow norm, asymptotic Chow stability, CSC Kähler metrics, strong K-stability, the Kodaira embedding have to be replaced by

(2) polybalanced metrics, the weighted Chow norm, asymptotic relative Chow stability, extremal Kähler metrics, strong relative K-stability, the weighted Kodaira embedding, respectively.

Thank you.