

CHAPTER 3
SOME PLANE TOPOLOGY

In this chapter we study in a deeper way the case of the plane \mathbf{R}^2 .

1. Jordan's theorem for the circle.

Theorem 1.1. (Jordan's theorem for the circle). *Let $j : \mathbf{R}^2 \hookrightarrow \mathbf{S}^1$ be a continuous injective map. The set $\mathbf{R}^2 \setminus j(\mathbf{S}^1)$ has exactly two connected components, one bounded and the other one unbounded.*

Proof. We know already that $\mathbf{R}^2 \setminus j(\mathbf{S}^1)$ has at least two connected components one of them being unbounded. We will suppose that there exists at least three connected components U_1, U_2 and U_3 in $\mathbf{R}^2 \setminus j(\mathbf{S}^1)$ and we will obtain a contradiction. Using 2.5.2, we can find two injective arcs $\alpha_1, \alpha_2 : [0, 1] \rightarrow \mathbf{R}^2$ such that $\partial\alpha_i \subset j(\mathbf{S}^1), \alpha_i \setminus \partial\alpha_i \subset U_i$, for $i = 1, 2$, and the four points $A_1 = \alpha_1(0), A_2 = \alpha_2(0), B_1 = \alpha_1(1)$, and $B_2 = \alpha_2(1)$ are distinct and cyclically ordered on $j(\mathbf{S}^1)$ (see figure 1.1). Let us call $[A_1, A_2]$ and $[B_1, B_2]$ the two disjoint closed subarcs of $j(\mathbf{S}^1)$ determined by the four points A_1, A_2, B_1 and B_2 . The set $\gamma = [A_1, A_2] \cup \alpha_2([0, 1]) \cup [B_2, B_1] \cup \alpha_1([1, 0])$ is homeomorphic to \mathbf{S}^1 ; in particular, we know

that $\mathbf{R}^2 \setminus \gamma$ is not connected. Remark that, by construction, we have $U_3 \subset \mathbf{R}^2 \setminus \gamma$. Let V be the connected component of $\mathbf{R}^2 \setminus \gamma$ containing the connected set U_3 . Since $U_3 \cup]B_2, A_1[\cup]B_1, A_2[$ is connected—contained between U_3 and its closure $U_3 \cup j(\mathbf{S}^1)$ —and it is disjoint from γ , it is contained in V . It follows that $j(\mathbf{S}^1) \subset V \cup \gamma$. Let W be a connected component of $\mathbf{R}^2 \setminus \gamma$ distinct from V . The set W does not intersect $j(\mathbf{S}^1)$, but, since $\overline{W} \supset \alpha_1 \cap \alpha_2$, it intersects two distinct connected components of its complement, namely U_1 and U_2 . This is a contradiction. \square

Remark 1.2. This proof, due to Whyburn, is quite magic. We will give a more palatable proof later on.

Definition 1.3. (Interior and exterior). Let $\gamma \subset \mathbf{R}^2$ be a simple closed curve. Its interior component— or simply interior, if there no possible confusion— is the bounded component of $\mathbf{R}^2 \setminus \gamma$, it is denoted by $\mathbb{I}(\gamma)$. Its exterior component— or simply exterior, if there no possible confusion— is the unbounded component of $\mathbf{R}^2 \setminus \gamma$, it is denoted by $\mathbb{E}(\gamma)$.

2. The set of homotopy classes of maps to the circle.

We identify \mathbf{R}^2 to \mathbf{C} . In this identification, \mathbf{S}^1 becomes the unit circle in \mathbf{C} , and is naturally a group for the multiplication of complex numbers. In fact, \mathbf{S}^1 is a topological compact metric abelian group. If $f, g : X \rightarrow \mathbf{S}^1$ are two continuous maps the pointwise product $fg : X \rightarrow \mathbf{S}^1, x \mapsto f(x)g(x)$, is also a continuous map. In particular, the set of continuous maps from X to \mathbf{S}^1 , denoted by $\mathcal{C}(X, \mathbf{S}^1)$, is an abelian group for this multiplication.

Lemma 2.1. *The group structure on $\mathcal{C}(X, \mathbf{S}^1)$ induces on $[X, \mathbf{S}^1]$ a structure of abelian group. The neutral element in $[X, \mathbf{S}^1]$ is the class of null homotopic maps.*

Proof. Exercise! \square

Notation 2.2. The (surjective) exponential map $\mathbf{R} \rightarrow \mathbf{S}^1, x \mapsto e^{2i\pi x}$, will be denoted by \exp . We have $\exp(x) = 1$ if and only if $x \in \mathbf{Z}$. Moreover, \exp has a continuous inverse above any proper subset of \mathbf{S}^1 .

Theorem 2.3. A map $f : X \rightarrow \mathbf{S}^1$ is null homotopic if and only if there exists a lifting \bar{f} of f to a continuous map $\bar{f} : X \rightarrow \mathbf{R}$ with $\exp \circ \bar{f} = f$.

We need some lemmas to prove theorem 2.3.

Lemma 2.4. Let K, X, Y be three spaces with K compact and Y metric. Endow the set $\mathcal{C}(K, Y)$ of continuous maps from K to Y with the topology of uniform convergence. There is a natural bijection between $\mathcal{C}(X \times K, Y)$ and $\mathcal{C}(X, \mathcal{C}(K, Y))$; it associates to the map $f : X \times K \rightarrow Y$ the map $f^\# : X \rightarrow \mathcal{C}(K, Y)$ defined by $f^\#(x)(k) = f(x, k)$.

Proof. Exercise! □

Lemma 2.5. The map $\varphi \mapsto \exp \varphi$ establishes a homeomorphism between the spaces $\mathcal{C}_0([0, 1], \mathbf{R}) = \{\varphi \in \mathcal{C}([0, 1], \mathbf{R}) \mid \varphi(0) = 0\}$ and $\mathcal{C}_1([0, 1], \mathbf{S}^1) = \{\theta \in \mathcal{C}([0, 1], \mathbf{S}^1) \mid \theta(0) = 1\}$ (the topology on set of maps is the topology of uniform convergence).

Proof. (Sketch). The map is a continuous homomorphism of topological groups. It is injective, because $\exp \circ \varphi = 1$ implies $\varphi(x) \in \mathbf{Z}, \forall x \in [0, 1]$. By the connectedness of $[0, 1]$, this implies $\varphi(x) = \varphi(0) = 0, \forall x \in [0, 1]$. Since the two groups are connected—exercise!—it suffices to check that there is a continuous section on a neighborhood of the constant map 1 in $\mathcal{C}_1([0, 1], \mathbf{S}^1)$. Such a section is obtained by composition with a fixed continuous section of $\exp : \mathbf{R} \rightarrow \mathbf{S}^1$ above $\{z \in \mathbf{S}^1 \mid |z - 1| < 2\}$. □

The following theorem is more general than 2.3.

Theorem 2.6. Let $F : X \times [0, 1] \rightarrow \mathbf{S}^1$ be a continuous map. If $f : X \rightarrow \mathbf{R}$ is a continuous map such that $F|X \times \{0\} = \exp \circ f$, then there exists a continuous map $\bar{F} : X \times [0, 1] \rightarrow \mathbf{R}$ with $\exp \circ \bar{F} = F$ and $\bar{F}|X \times \{0\} = f$. In particular, $F|X \times \{1\}$ can be lifted to a continuous map $X \rightarrow \mathbf{R}$.

Proof. Define $F' : X \times [0, 1] \rightarrow \mathbf{S}^1$ by $F'(x, t) = F(x, t) \exp(-f(x))$. We have $F'|X \times \{0\} = 1$. It follows from 2.4 and 2.5, that we can lift F' to a continuous map $\bar{F}' : X \times [0, 1] \rightarrow \mathbf{R}$, with $\bar{F}'|X \times \{0\} = 0$. The map \bar{F} is defined by $\bar{F}(x, t) = \bar{F}'(x, t) + f(x)$. □

Proof of 2.3. Since a constant map can be lifted, by 2.6, a null homotopic map $f : X \rightarrow \mathbf{S}^1$ can be lifted to a continuous map $\bar{f} : X \rightarrow \mathbf{R}$ such that $\exp \circ \bar{f} = f$. Of course, since \mathbf{R} is contractible, a map of the form $\exp \circ \bar{f} = f$ is null homotopic. □

Corollary 2.7. For each topological space X , the group $[X, \mathbf{S}^1]$ has no torsion.

Proof. Let $f : X \rightarrow \mathbf{S}^1$ be a continuous map. If $n > 0$ is such that $f^n \sim 0$, by 2.3, there exists a continuous map $g : X \rightarrow \mathbf{R}$ with $\exp(g(x)) = f^n(x)$. It follows that the sets $X_j = \{x \in X \mid f(x) = \exp[g(x) + j]/n\}, j = 0, \dots, n-1$, form a partition of X into closed sets. A lifting $\bar{f} : X \rightarrow \mathbf{R}$ is obtained by defining it on X_j by $\bar{f}(x) = [g(x) + j]/n$. □

Theorem 2.8. *The group $[\mathbf{S}^1, \mathbf{S}^1]$ is infinite cyclic. More precisely, the homomorphism $\mathbf{Z} \rightarrow [\mathbf{S}^1, \mathbf{S}^1]$, which sends 1 to the homotopy class of $\text{Id}_{\mathbf{S}^1}$, is an isomorphism.*

Proof. Since $\text{Id}_{\mathbf{S}^1}$ is essential by 2.7, the map is injective. Let $f: \mathbf{S}^1 \rightarrow \mathbf{S}^1$ be a continuous map. Since $[0, 1]$ is contractible, we can lift $f \circ \exp: [0, 1] \rightarrow \mathbf{S}^1$ to a map $\bar{f}: [0, 1] \rightarrow \mathbf{R}$, this means that $\exp \circ \bar{f} = f \circ \exp$. In particular $n = \bar{f}(1) - \bar{f}(0) \in \mathbf{Z}$, since $\exp(\bar{f}(1)) = f(\exp(1)) = f(\exp(0)) = \exp(\bar{f}(0))$. Remark now that the map $\bar{\varphi}(t) = \bar{f}(t) - nt$ verifies $\bar{\varphi}(0) = \bar{\varphi}(1)$, so we can define a continuous map $\mathbf{S}^1 \rightarrow \mathbf{R}$ by $\varphi \circ \exp|_{[0, 1]} = \bar{\varphi}$. The formula $\bar{\varphi}(t) = \bar{f}(t) - nt$ gives $\exp(\varphi(z)) = f(z)z^{-n}, \forall z \in \mathbf{S}^1$; this shows that f is homotopic to n times $\text{Id}_{\mathbf{S}^1}$. \square

Definition 2.9. (Degree). If $f: \mathbf{S}^1 \rightarrow \mathbf{S}^1$ is a continuous map, the degree of f , denoted by $\text{deg}(f)$, is the integer n such that f is homotopic to $z \mapsto z^n$.

Theorem 2.10. *Let X be a metric space which is a countable union of closed sets $F_n, n \in \mathbf{N}$, such that:*

- (i) $\forall n \in \mathbf{N}, F_n$ is connected,
- (ii) $\forall n \in \mathbf{N}, F_n \subset F_{n+1}$,
- (iii) each compact subset of X is contained in one of the F_n —this condition follows, for example, from the stronger one $F_n \subset \text{Int}(F_{n+1})$.

Then we have:

- (a) a continuous map $f: X \rightarrow \mathbf{S}^1$ is null homotopic if and only if for each $n \in \mathbf{N}$ the restriction $f|_{F_n}$ is null homotopic,
- (b) if, for each $n \in \mathbf{N}$, we have a continuous map $f_n: F_n \rightarrow \mathbf{S}^1$, with $f_{n+1}|_{F_n} \sim f_n$, then there exists a continuous map $f: X \rightarrow \mathbf{S}^1$ with $f|_{F_n} \sim f_n, \forall n \in \mathbf{N}$.

In other terms, if we look at the projective system: $\cdots [F_{n+1}, \mathbf{S}^1] \xrightarrow{r_{n+1}} [F_n, \mathbf{S}^1] \xrightarrow{r_n} \cdots$, where $r_{n+1}([f]) = [f|_{F_n}]$, then $[X, \mathbf{S}^1]$ can be identified to the projective limit $P = \varprojlim ([F_n, \mathbf{S}^1], r_n)$; the map $[X, \mathbf{S}^1] \rightarrow P$ is given by $[f] \mapsto ([f|_{F_n}]_{n \in \mathbf{N}})$.

Proof. To prove (a), it suffices to show that if a map $f: X \rightarrow \mathbf{S}^1$ is such that, for each $n \in \mathbf{N}$, there exists a continuous lift $\bar{f}_n: F_n \rightarrow \mathbf{R}$ with $f|_{F_n} = \exp \circ \bar{f}_n$, then we can define a continuous lift $\bar{f}: X \rightarrow \mathbf{R}$ with $f = \exp \circ \bar{f}$. We construct $\bar{f}|_{F_n}$ by induction. We start with $\bar{f}|_{F_0} = \bar{f}_0$. Suppose that we have constructed $\bar{f}|_{F_n}$. Since $\bar{f}|_{F_n}$ and $\bar{f}_{n+1}|_{F_n}$ are two lifts of f , the map $\bar{f}|_{F_n} - \bar{f}_{n+1}|_{F_n}$ lifts a constant map. By the connectedness of F_n , we obtain $\bar{f}|_{F_n} - \bar{f}_{n+1}|_{F_n} = c_n$, where c_n is a constant. It suffices to define $\bar{f}|_{F_{n+1}}$ as $\bar{f}_{n+1} + c_n$. this shows that we have a well defined lifting $\bar{f}: X \rightarrow \mathbf{R}$, with $\bar{f}|_{F_n}$ continuous for each $n \in \mathbf{N}$. Condition (iii) implies that \bar{f} is itself continuous. In fact, since X is metric, it suffices to check continuity on compact subsets, because a convergent sequence together with its limit is a compact subset. Continuity of \bar{f} on compact subsets of X is forced by (iii). To prove (b), we construct $f|_{F_n}$ by induction. We start with $f|_{F_0} = f_0$. Suppose that we have constructed $f|_{F_n} \sim f_n$, then we have $f|_{F_n} \sim f_{n+1}|_{F_n}$. By the homotopy extension theorem 2.1.10, we can find a continuous map $f|_{F_{n+1}}: F_{n+1} \rightarrow \mathbf{S}^1$, homotopic to f_{n+1} , and whose restriction to F_n is precisely $f|_{F_n}$. The continuity of f is proven in the same lines as we did it above for \bar{f} . \square

Lemma 2.11. *Let X be a locally connected space, and let $(X_i)_{i \in I}$ be the family of its connected components. The restriction map, $f \mapsto (f|X_i)_{i \in I}$, induces an isomorphism between $[X, \mathbf{S}^1]$ and $\prod_{i \in I} [X_i, \mathbf{S}^1]$.*

Proof. Exercise! □

Corollary 2.12. *Let X be a locally connected metric space which is a countable union of closed sets $F_n, n \in \mathbf{N}$, such that:*

- (i) $\forall n \in \mathbf{N}, \forall C$ connected component of X , the set $C \cap F_n$ is connected,
- (ii) $\forall n \in \mathbf{N}, F_n \subset F_{n+1}$,
- (iii) each compact subset of X is contained in one of the F_n .

Then $[X, \mathbf{S}^1]$ is isomorphic to the projective limit of the $[F_n, \mathbf{S}^1]$ under the restriction maps.

Proof. The proof is an easy exercise, using 2.10 and 2.11. □

3. Compact subsets in the plane.

Theorem 3.1. *Let K be a compact subset of the plane, and let $(U_i)_{i \in I}$ be the family of bounded connected components of $\mathbf{R}^2 \setminus K$. For each $i \in I$, we choose a point $a_i \in U_i$. The group $[K, \mathbf{S}^1]$ is a free abelian group with a basis given by the Borsuk maps $(\theta_{a_i})_{i \in I}$, where $\theta_{a_i} : K \rightarrow \mathbf{S}^1, \theta_{a_i}(x) = (x - a_i) / \|x - a_i\|$.*

Proof. We first show the independence of the θ_{a_i} . Suppose that we have $\theta_{a_{i_1}}^{n_1} \sim \prod_{j=2}^k \theta_{a_{i_j}}^{n_j}$, with $n_1 \in \mathbf{Z}, n_1 \neq 0$, and $a_{i_j} \neq a_{i_1}, \forall j \geq 2$. Since $a_{i_j} \notin U_{i_1}, \forall j \geq 2$, the map $\prod_{j=2}^k \theta_{a_{i_j}}^{n_j}$ can be extended to $U_{i_1} \cup K$ by the same formula. By the homotopy extension property 2.1.10, the map $\theta_{a_{i_1}}^{n_1}$ also extends to $U_{i_1} \cup K$. Since the formula defining θ_{a_1} makes sense outside $U_{i_1} \cup K$, we see that $\theta_{a_{i_1}}^{n_1}$ extends to \mathbf{R}^2 . This implies that $\theta_{a_{i_1}}^{n_1}$ is null homotopic, and by 2.7, since $n_1 \neq 0$ it follows that θ_{a_1} is also null homotopic. This contradicts theorem 2.3.3. We now prove that $(\theta_{a_i})_{i \in I}$ generates $[K, \mathbf{S}^1]$. Let $f : K \rightarrow \mathbf{S}^1$ be a continuous map. By 2.3.10, we can find a finite set a_{i_1}, \dots, a_{i_k} and an extension $\bar{f} : \mathbf{R}^2 \setminus \{a_{i_1}, \dots, a_{i_k}\}$. We choose small disks B_1, \dots, B_k centered around a_{i_1}, \dots, a_{i_k} and contained in U_{i_1}, \dots, U_{i_k} . We start with $f_0 = \bar{f}|_{\mathbf{R}^2 \setminus \cup_{j=1}^k \text{Int}(B_j)}$. We construct, by induction on $j = 1, \dots, k$, maps $f_j : \mathbf{R}^2 \setminus \cup_{l>j}^k \text{Int}(B_l)$ and integers n_j , such that f_j is an extension of $f_{j-1} \theta_{a_{i_j}}^{-n_j}$. Suppose that we have already constructed f_1, \dots, f_j and n_1, \dots, n_j . By 2.8, the map f_j restricted to S_{j+1} the frontier of B_{j+1} is homotopic to some power $\theta_{a_{i_{j+1}}}^{n_{j+1}}$ restricted to S_{j+1} ; in particular, we can extend $f_j \theta_{a_{i_{j+1}}}^{-n_{j+1}}|_{S_{j+1}}$ to a continuous map from B_{j+1} to \mathbf{S}^1 . This allows us to extend $f_j \theta_{a_{i_{j+1}}}^{-n_{j+1}}$ to a map $f_{j+1} : \mathbf{R}^2 \setminus \cup_{l>j+1}^k \text{Int}(B_l) \rightarrow \mathbf{S}^1$. We have $f_k \sim 0$, since it is defined on \mathbf{R}^2 ; moreover $f_k|_K = f \prod_{j=1}^k \theta_{a_{i_j}}^{-n_j}$. □

Corollary 3.2. (Jordan's theorem). *Let $j : \mathbf{S}^1 \hookrightarrow \mathbf{R}^2$ be an imbedding. The set $\mathbf{R}^2 \setminus j(\mathbf{S}^1)$ has exactly two connected components, one bounded and the other one unbounded. If x is a point in the bounded component of $\mathbf{R}^2 \setminus j(\mathbf{S}^1)$ then the degree of the composite map $\mathbf{S}^1 \xrightarrow{j} j(\mathbf{S}^1) \xrightarrow{\theta_x} \mathbf{S}^1$ is ± 1 .*

Proof. This follows from 3.1, since the map $j^* : [j(\mathbf{S}^1), \mathbf{S}^1] \rightarrow [\mathbf{S}^1, \mathbf{S}^1]$, which maps the homotopy class of f to that of $f \circ j$, is an isomorphism. \square

Definition 3.3. Let x and y be two points in a topological space X . The subset A of X separates x and y (in X) if x and y belong to distinct connected components of $X \setminus A$.

The following proposition is easily seen to be a particular case of 2.3.6.

Proposition 3.4. *Two points a, b in \mathbf{R}^2 are separated by the compact subset K if and only if the map $\theta_{a,b} : K \rightarrow \mathbf{S}^1, z \mapsto \frac{z-a}{\|z-a\|} \frac{\|z-b\|}{z-b}$ is essential.*

Theorem 3.5. (Janizewski lemma). *Let K be a compact subset in \mathbf{R}^2 such that $K = K_1 \cup K_2$, with K_1, K_2 compact and $K_1 \cap K_2$ connected. Two points in $\mathbf{R}^2 \setminus K$ are separated by K if and only if they are separated either by K_1 or by K_2 .*

By proposition 3.4, the theorem is a consequence of the following lemma.

Lemma 3.6. *Let A be a compact space which is a union of two compact subsets A_1 and A_2 with $A_1 \cap A_2$ connected. A map $f : A \rightarrow \mathbf{S}^1$ is null homotopic if and only if $f|_{A_1}$ and $f|_{A_2}$ are null homotopic.*

Proof. If $f|_{A_1}$ and $f|_{A_2}$ are null homotopic, by theorem 2.3, we can write $f|_{A_i} = \exp \circ \varphi_i$, where $\varphi_i : A_i \rightarrow \mathbf{R}$, for $i = 1, 2$. Since $\exp \circ (\varphi_1 - \varphi_2)|_{A_1 \cap A_2} = (f/f)|_{A_1 \cap A_2} = 1$ and $A_1 \cap A_2$ is connected, the map $(\varphi_1 - \varphi_2)|_{A_1 \cap A_2}$ is constant. If we call k its value, we see that we can define a lift $\varphi : A \rightarrow \mathbf{R}$ of f by $\varphi|_{A_1} = \varphi_1 + k$ and $\varphi|_{A_2} = \varphi_2$. The other half of the lemma is trivial. \square

Corollary 3.7. (Janizewski lemma). *Let K and F be respectively a compact and a closed subset in \mathbf{R}^2 such that $K \cap F$ is connected. Two points in $\mathbf{R}^2 \setminus K \cup F$ are separated by $K \cup F$ if and only if they are separated either by K or by F .*

Proof. If two points in $\mathbf{R}^2 \setminus K \cup F$ are separated either by K or by F , they are of course separated by the larger set $K \cup F$. Suppose now that a and b are two points which are contained in the same connected component of $\mathbf{R}^2 \setminus F$; since this set is locally arcwise connected—as is any open set in \mathbf{R}^2 —we can find a compact connected subset C of $\mathbf{R}^2 \setminus F$ which contains a and b . Let R be big enough to have $C \cup K$ contained in the interior of the ball $B(0, R)$. By construction a and b are not separated by $F \cup \partial B(0, R)$ —the connected set C is disjoint from $F \cup \partial B(0, R)$. Suppose now that a and b are not separated by K . Since $K \cap [\partial B(0, R) \cup (F \cap B(0, R))] = K \cap F$ is connected, by 3.5 we obtain that a and b are not separated by the compact set $K \cup \partial B(0, R) \cup (F \cap B(0, R))$. In particular, there is a connected set A containing a and b and disjoint from $K \cup \partial B(0, R) \cup (F \cap B(0, R))$. Since a and b are in the interior of $B(0, R)$, the set A is also contained in $B(0, R)$ and is consequently disjoint from F . \square

Corollary 3.8. *Let U be an open connected subset of \mathbf{R}^2 and let K be a compact subset in \mathbf{R}^2 such that $K \setminus U$ is connected. Two points in U are separated by K in U if and only if they are separated either by K in \mathbf{R}^2 .*

Proof. Let $F = \mathbf{R}^2 \setminus U$. Since U is connected any two points cannot be separated by F . By 3.7 two points are separated by $K \cup F$ if and only if they are separated by K . \square

The following is a useful special case of 3.8.

Corollary 3.9. *Let U be an open connected subset of \mathbf{R}^2 . Let α be an arc in \mathbf{R}^2 such that $\partial\alpha$ is contained in a compact connected subset C of $\mathbf{R}^2 \setminus U$, and $\alpha \setminus \partial\alpha$ is contained in U . Distinct connected components of $U \setminus \alpha$ are contained in distinct connected components of $\mathbf{R}^2 \setminus (\alpha \cup C)$.*

4. Open subsets of the plane.

Theorem 4.1. *Let U be a connected open subset in \mathbf{R}^2 . We can find a family $(K_i)_{i \in \mathbf{N}}$ of compact subsets of U , such that:*

- (i) *each K_i is connected;*
- (ii) *for each $i \in \mathbf{N}$, $K_i \subset \text{Int}(K_{i+1})$;*
- (iii) *for each $i \in \mathbf{N}$, the set $\mathbf{R}^2 \setminus K_i$ has a finite number of connected components, and each relatively compact component of $\mathbf{R}^2 \setminus K_i$ contains a compact component of $\mathbf{R}^2 \setminus U$;*
- (iv) *if x and y are contained in different connected components of $\mathbf{R}^2 \setminus U$, and one of them is contained in a compact component of $\mathbf{R}^2 \setminus U$, then there exists i_0 such that x and y are contained in different connected components of $\mathbf{R}^2 \setminus K_{i_0}$.*

Corollary 4.2. *Let U be an open connected subset in \mathbf{R}^2 . The group $[U, \mathbf{S}^1]$ is not reduced to zero if and only if $\mathbf{R}^2 \setminus U$ has a compact component. Moreover, if c is in a compact component of $\mathbf{R}^2 \setminus U$, the Borsuk map $\theta_c : U \rightarrow \mathbf{S}^1, x \mapsto (x - c)/\|x - c\|$ is not null homotopic and it is indivisible in $[U, \mathbf{S}^1]$.*

Proof. Suppose that $\mathbf{R}^2 \setminus U$ has no compact component. Let $(K_n)_{n \in \mathbf{N}}$ be given by 4.1. Property (iii) of 4.1 implies that each $\mathbf{R}^2 \setminus K_n$ has only unbounded components. By 3.1, we have $[K_n, \mathbf{S}^1] = 0$ for each $n \in \mathbf{N}$. By 2.10, this implies that $[U, \mathbf{S}^1] = 0$. Suppose now that C is a compact component of $\mathbf{R}^2 \setminus U$. By 3A.1.4, we can find an open relatively compact subset V of \mathbf{R}^2 , with $C \subset V$ and $\text{Fr} V \subset U$. of course, the compact set C is contained in a relatively compact component of $\mathbf{R}^2 \setminus \text{Fr} V$. This implies that if $c \in C$ the Borsuk map $\theta_c : \mathbf{R}^2 \setminus \{c\} \rightarrow \mathbf{S}^1$ is such that $\theta_c|_{\text{Fr} V}$ is essential and indivisible. Since $\text{Fr} V \subset U$, the restriction $\theta_c|_U$ is also essential and indivisible \square

Corollary 4.3. *Let U be an open connected subset in \mathbf{R}^2 such that $\mathbf{R}^2 \setminus U$ has a finite number of compact components C_1, \dots, C_k . Choose for each $i = 1, \dots, k$, a point $c_i \in C_i$. Let $\theta_i : U \rightarrow \mathbf{S}^1, x \mapsto (x - c_i) / \|x - c_i\|$ be the Borsuk map with respect to c_i . The group $[U, \mathbf{S}^1]$ is the free abelian group generated by the homotopy classes of the θ_i .*

Proof.

Theorem 4.4. *Let U be a connected open subset in \mathbf{R}^2 . The following statements are equivalent:*

- (i) $\mathbf{R}^2 \setminus U$ has no compact connected component;
- (ii) each continuous map $\varphi : U \rightarrow \mathbf{S}^1$ can be lifted to a continuous map $\bar{\varphi} : U \rightarrow \mathbf{R}$;
- (iii) each continuous map $\theta : U \rightarrow \mathbf{C} \setminus \{0\}$ can be lifted to a continuous map $\bar{\theta} : U \rightarrow \mathbf{C}$, with $\theta = \exp \circ \bar{\theta}$;
- (iv) each holomorphic map $\theta : U \rightarrow \mathbf{C} \setminus \{0\}$ can be lifted to a holomorphic map $\bar{\theta} : U \rightarrow \mathbf{C}$, with $\theta = \exp \circ \bar{\theta}$;
- (v) each continuous map $\theta : U \rightarrow \mathbf{C} \setminus \{0\}$ has a continuous square root;
- (vi) each holomorphic map $\theta : U \rightarrow \mathbf{C} \setminus \{0\}$ has a holomorphic square root.

Proof. (i) \Leftrightarrow (ii) follows from 4.3. (ii) \Leftrightarrow (iii) follows from the fact that a continuous map with values in $]0, \infty[$ has a continuous logarithm. (iii) \Rightarrow (iv) is clear. (iv) \Rightarrow (i) follows from 4.2. (iii) \Rightarrow (v) \Rightarrow (vi) are easy. (vi) \Rightarrow (ii) follows from 4.2. \square